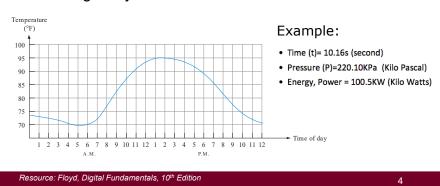
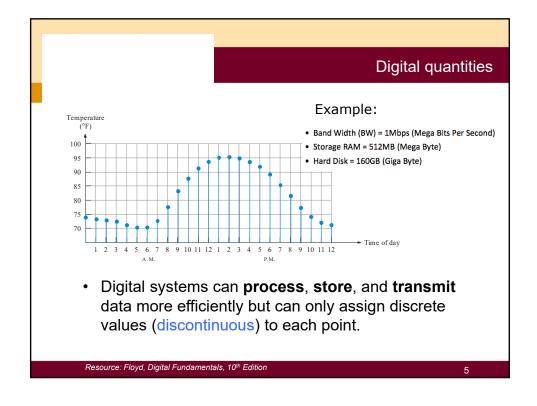
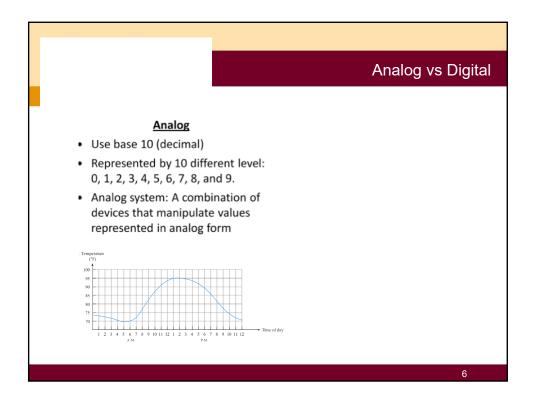


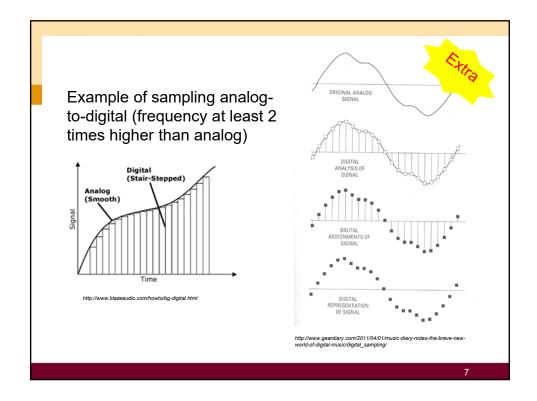
# Analog quantities

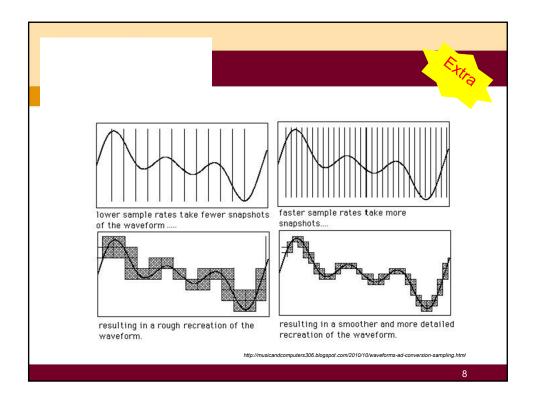
- Most natural quantities that we see are analog and vary continuously.
- Analog systems can generally handle higher power than digital systems.



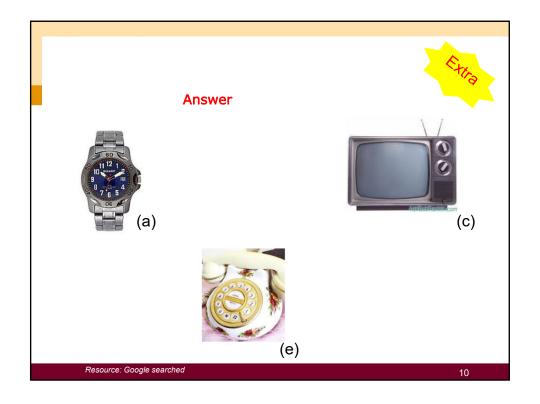


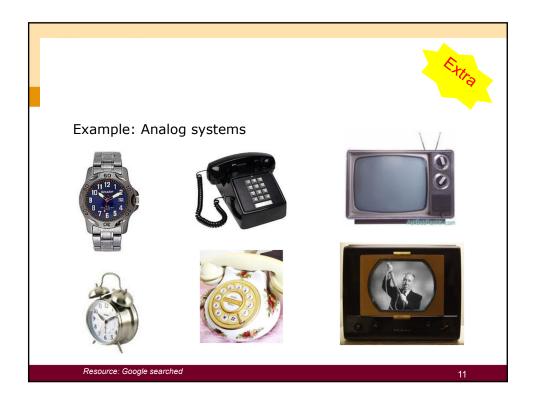














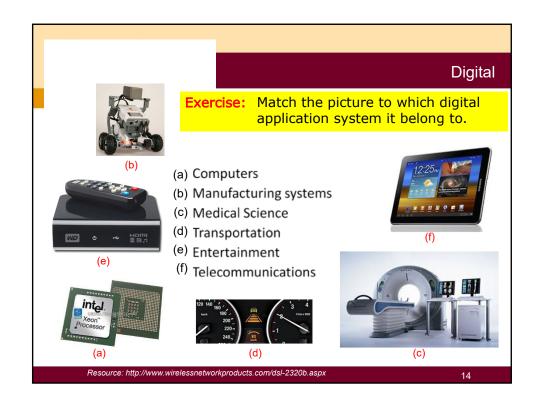
#### Digital

- Digital technology is relatively new compared to analog technology, but a lot of analog systems has been changed to a digital systems, Examples:
  - Computers
  - Manufacturing systems
  - Medical Science
  - Transportation
  - Entertainment
  - Telecommunications



\*DSL-2320B (ADSL Modem)

Resource: http://www.wirelessnetworkproducts.com/dsl-2320b.aspx



# **The Digital Advantages**



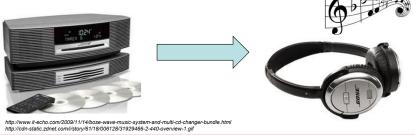
- Ease of design
- Ease of storage
- Accuracy and precision are easier to maintain
- Programmable operation
- Less affected by noise
- Ease of fabrication on IC chips
  - ☐ Thus, the digital systems is more efficient and reliable for:
    - Data Processing
    - Data Transmission
    - Data Storage

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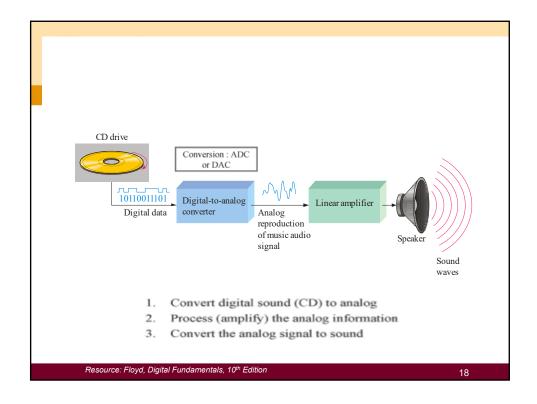
# Digital Disadvantages • Greater bandwidth • Sampling error Sampling Error (Quantization Error): is derived from Analog to Digital Conversion Process: Analog Sampling & Quantization Bit 0 and 1 • Compatibility with existing analog systems • Short product half life

# Analog and Digital Systems

- Many systems use a mix of analog and digital electronics to take advantage of each technology.
- A typical CD player accepts digital data from the CD drive and converts it to an analog signal for amplification.



Resource: Floyd, Digital Fundamentals, 10th Edition





- The audio CD is a typical hybrid (Analog & Digital) system.
  - Analog sound is converted into analog voltage using a microphone.
  - Analog voltage is changed into digital through an ADC in the recorder.
  - · Digital information is stored on the CD.
  - At playback the digital information is changed into analog by a DAC in the CD player.
  - The analog voltage is amplified and used to drive a speaker that produces the original analog sound.

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#### **Conversion:**

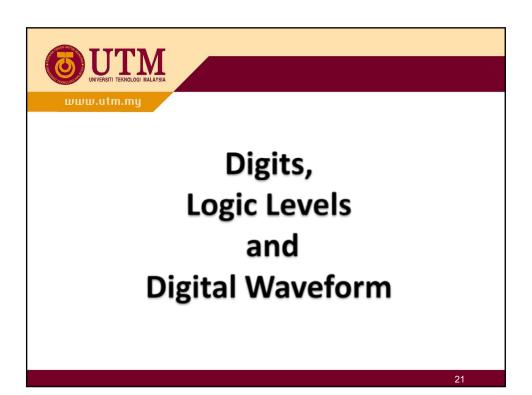
# 

#### Analog to Digital Converter (ADC):

- Convert analog signal into digital signal using process such as sampling, quantization process and digital conversion.
- Error will occur during the sampling and quantization, hence loss of information can happen.

## Digital to Analog Converter (DAC):

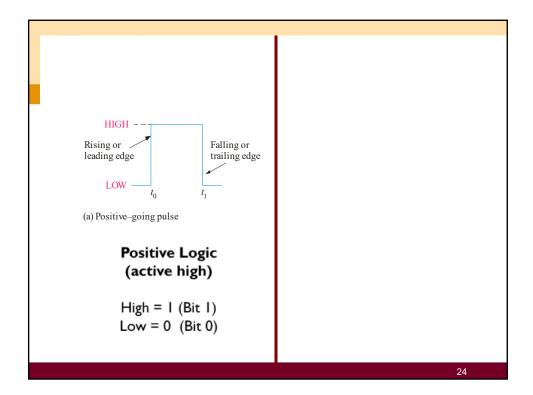
- · Needed if the speaker is using analog system.
- Need to convert the digital data to analog signal in order for the speaker works properly and the sound can heard by human.

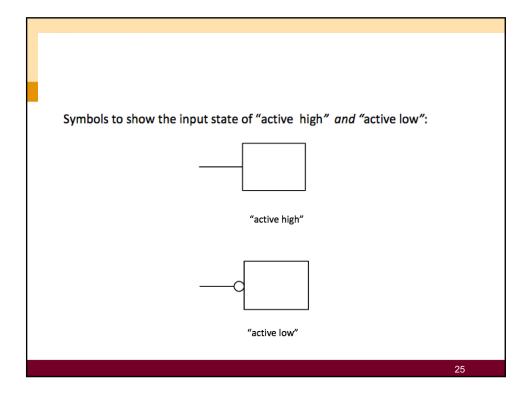


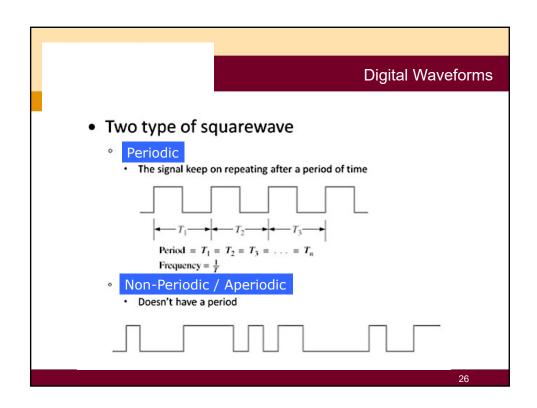
#### Binary digits and logic levels Digital electronics uses circuits that have two states, which are represented by HIGH two different voltage levels: $V_{H(min)}$ Invalid $V_{L(max)}$ HIGH (bit 1) LOW LOW (bit 0) $V_{L(min)}$ A bit can have the value of either a 0 or a 1, depending on if the voltage is HIGH or LOW. 1010100 represented as electrical signal Resource: Floyd, Digital Fundamentals, 10th Edition

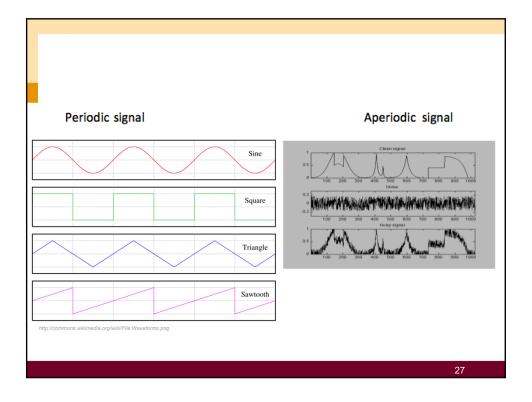
- Digital waveforms change between the LOW and HIGH levels.
- A positive going pulse is one that goes from a normally LOW logic level to a HIGH level and then back again.
- Digital waveforms are made up of a series of pulses.

Resource: Floyd, Digital Fundamentals, 10th Edition









# **Periodic Signal Parameter**

☐ Frequency (f) is the rate at which the signal repeat itself at a fixed interval. Is measured in cycles per second or Hertz (Hz)

 $f = \frac{1}{T}$  Hz

☐ Period (T) is the time from the edge of one pulse to the corresponding edge of the next pulse. Is measured in second

 $T = \frac{1}{f}$  seconds

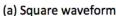
# **■** Example:

■ clock frequency : f = 100Hz, so, period : T = 1/100Hz =  $0.01s = 10x 10^{-3} = 10 ms$ 

> s  $\rightarrow$  ms (x 10<sup>3</sup>) ms  $\rightarrow$  s (x 10<sup>-3</sup>)

Some examples of periodic signal display on the oscilloscope:



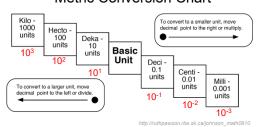




(b) Sinusoid waveform

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#### Metric Conversion Chart



# **Unit Conversion**

- Kilo (K)=  $10^3$
- Mega (M)= 10<sup>6</sup>
- Giga (G)= 10<sup>9</sup>
- Tera (T)=  $10^{12}$
- Mili (m)= 10<sup>-3</sup>
- Micro ( $\mu$ ) = 10<sup>-6</sup>
- Nano (n)= 10-9
- Piko (p) =  $10^{-12}$

```
• Mili (m)= 10<sup>-3</sup>
                                                             • Micro (\mu) = 10<sup>-6</sup>
                                                             • Nano (n)= 10-9
                                                             • Piko (p) = 10^{-12}
                Example: f = 100KHz, So
                              T = 1/f
                                = 1/(100*10^3Hz)
                                = 0.01*10^{-3} s
                ----- = 0.01ms
                                = 10 \mu s
                                            -----
= (0.01 * 10^{-3}) s x 10^{3}
                                                = (0.01 * 10^{-3}) s x 10^{6}
= (0.01 * 10^{-3+3}) \text{ ms}
                                                = (0.01 * 10^{-3+6}) \mu s
= (0.01 * 10^{\circ}) \text{ ms}
                                                = (0.01 * 10^3) \mu s
= 0.01 \text{ ms}
                                                = 10 \mu s
```

# **Exercise 1.1:** Calculate the frequency of signals if time period are given as the following:

- a) 10ms =\_\_\_\_\_\_
- b)  $100\mu s = _____KHz$
- c) 100ns = MHz
- d)  $1000 ps = ____GHz$



#### Solution 1.1:

a) 
$$10ms$$
 =  $(\frac{10}{10^3})s = (\frac{1}{10^2})s = 0.01s$   $f = \frac{1}{0.01} = 100Hz$ 

b) 
$$100 \mu s = (\frac{100}{10^6})s = (\frac{1}{10^4})s = 0.0001s$$

c) 
$$100ns = (\frac{100}{10^9})s = (\frac{1}{10^7})s = 10^{-7}s$$

d) 
$$1000 ps = (\frac{1000}{10^{12}})s = (\frac{1}{10^9})s = 10^{-9}$$

$$f = \frac{1}{0.01} = 100$$
Hz

b) 
$$100\mu s = (\frac{100}{10^6})s = (\frac{1}{10^4})s = 0.0001s$$
  $f = \frac{1}{0.0001} = 1 \times 10^4 Hz = \frac{1 \times 10^4}{10^3} = 10 KHz$ 

c) 
$$100ns = (\frac{100}{10^9})s = (\frac{1}{10^7})s = 10^{-7}s$$
  $f = \frac{1}{10^{-7}} = 1 \times 10^7 Hz = \frac{1 \times 10^7}{10^6} = 10 MHz$ 

d) 
$$1000ps = (\frac{1000}{10^{12}})s = (\frac{1}{10^9})s = 10^{-9}s$$
  $f = \frac{1}{10^{-9}} = 1 \times 10^9 Hz = \frac{1 \times 10^9}{10^9} = 1 GHz$ 

Exercise 1.2: Calculate the time period of signals if the frequencies are given as the following:

a) 
$$1000KHz = ____ \mu s$$

b) 
$$100MHz = ____ns$$

d) 
$$100THz = ____ps$$



#### Solution 1.2:

a) 
$$1000KHz = 1000 \times 10^3 Hz = 10^6 Hz$$

b) 
$$100MHz = 100 \times 10^6 Hz = 10^8 Hz$$

c) 
$$1000GHz^{\frac{1}{2}} = 1000 \times 10^9 Hz = 10^{12} Hz$$

d) 
$$100THz = 100 \times 10^{12} Hz = 10^{14} Hz$$

$$T = \frac{1}{10^6} = 10^{-6} s = 10^{-6} \times 10^6 = 1 \mu s$$

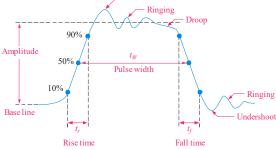
$$T = \frac{1}{10^8} = 10^{-8} \, s = 10^{-8} \times 10^9 = 10 \, ns$$

$$1000GHz = 1000 \times 10^{9} Hz = 10^{12} Hz$$
$$T = \frac{1}{10^{12}} = 10^{-12} s = 10^{-12} \times 10^{12} = 1ps$$

$$T = \frac{1}{10^{14}} = 10^{-14} s = 10^{-14} \times 10^{12} = 0.01 ps$$

#### **Pulse Definition**

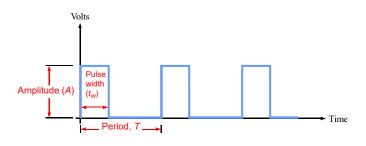
- Pulse is a rapid, transient change in the amplitude of a signal from a baseline value to a higher or lower value, followed by a rapid return to the baseline value.
- Pulse width  $(t_w)$ : A measure of the duration of the pulse.
- · Rise time and fall time is a measure of how fast the pulse change.



Resource: Floyd, Digital Fundamentals, 10th Edition

#### Repetitive Pulse Waveform

- In addition to frequency and period, repetitive pulse waveforms are described by the amplitude (A), pulse width (t<sub>W</sub>) and duty cycle.
- Duty cycle is the ratio of  $t_W$  to T.



Resource: Floyd, Digital Fundamentals, 10th Edition

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# **Duty Cycle**

□ Duty cycle is the fraction of time that a system is in an "active" state (operated), defined as

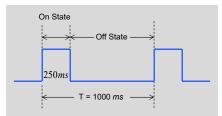
Duty cycle = 
$$(t_w/T)100\%$$



**Example**: a periodic digital waveform has a pulse width  $(t_w)$  1ms and period time (T) 10ms, calculate duty cycle?

Duty cycle = 1ms/10ms \* 100% = 10%

Exercise 1.3: Given the duration or period of a system is 1000ms, determine the *on state* and *off state* of the system that operate with the ratio of duty cycle is 25%. Show your works.



#### Solution 1.3:

Duty cycle → on state

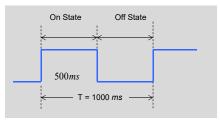
$$= 25\% \times 1000 ms = \frac{25}{100} \times 1000 ms = \frac{1}{4} \times 1000 ms = 250 ms$$

Off state : =1000ms - 250ms = 750ms

(module: page 18)

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Exercise 1.4: Given the duration or period of a system is 1000ms, determine the *on state* and *off state* of the system that operate with the ratio of duty cycle is 50%. Show your works.



#### Solution 1.4:

Duty cycle → on state

$$= 50\% \times 1000 ms = \frac{50}{100} \times 1000 ms = \frac{1}{2} \times 1000 ms = 500 ms$$

Off state : =1000ms - 500ms = 500ms

(module: page 18)

**Exercise 1.5:** Given the *duty cycles* of a system is 40% for a duration of a system is 500ms.

- a) Calculate the pulse width of the system.
- b) Determine the *off state* of the system that operate with the ratio of duty cycle. Show your works.

#### Solution 1.5:

a) 
$$DutyCycle = (\frac{t_W}{T})100$$
$$40 = (\frac{t_W}{500})100$$

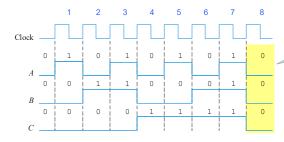
$$t_W = \frac{40(500)}{100} = 200s$$

b) Period = 500ms  $OnState = t_W = 200ms$  $\therefore 500 - 200 = 300ms$ 

(module: page 18)

## Timing diagram

A timing diagram is used to show the relationship between two or more digital waveforms,

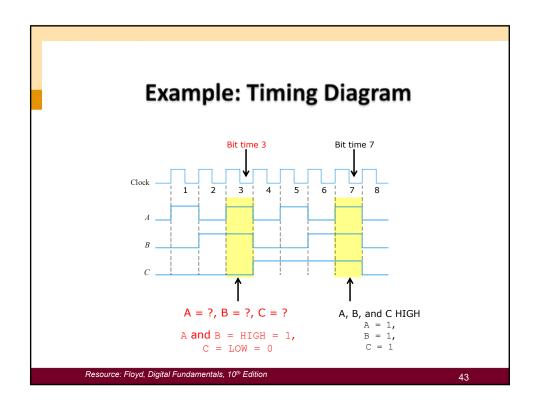


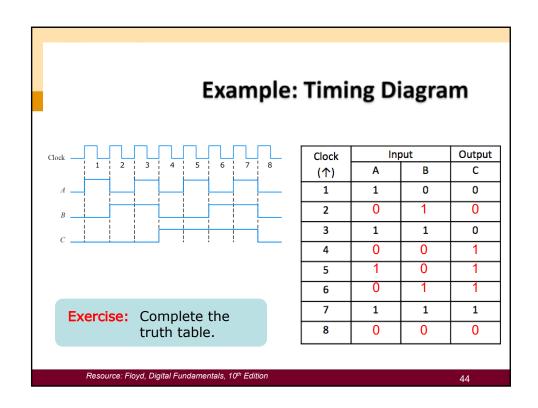
At time 8, all A, B, and C LOW

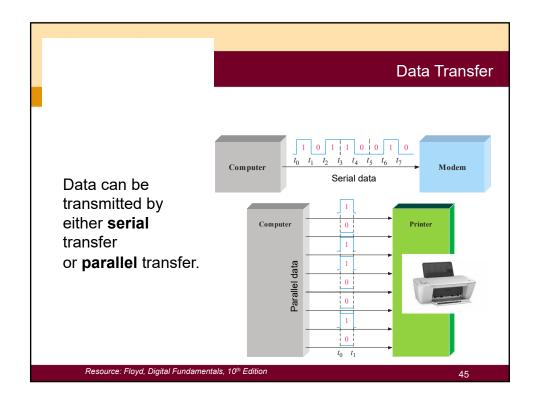
A diagram like this can be observed directly on a logic analyzer.

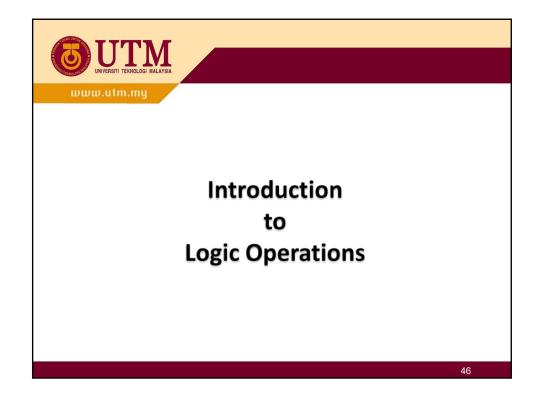


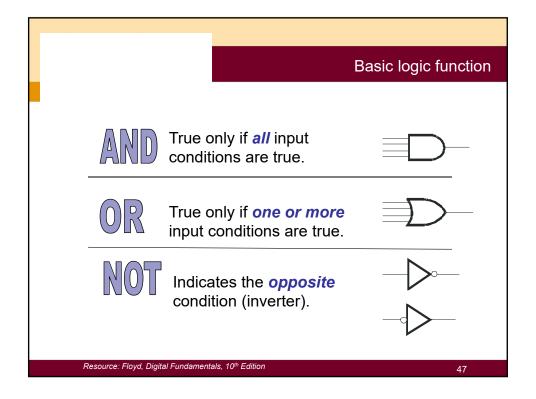
Resource: Floyd, Digital Fundamentals, 10<sup>th</sup> Edition

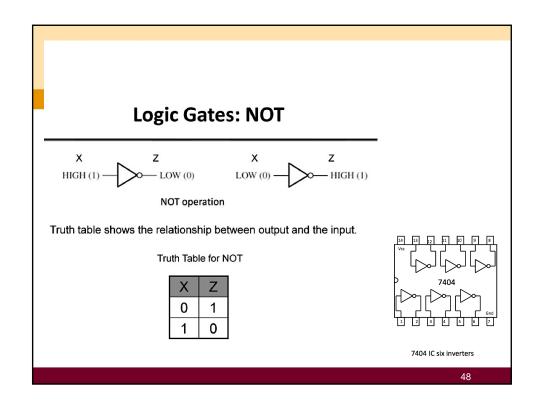


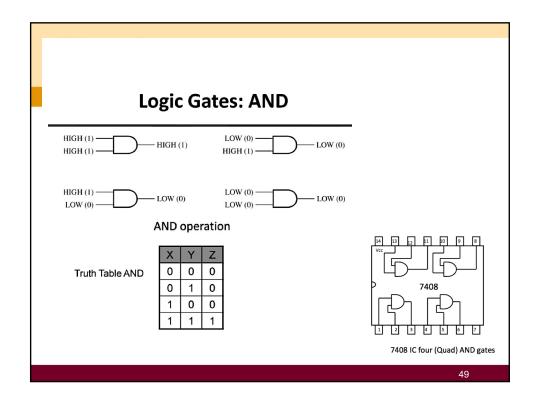


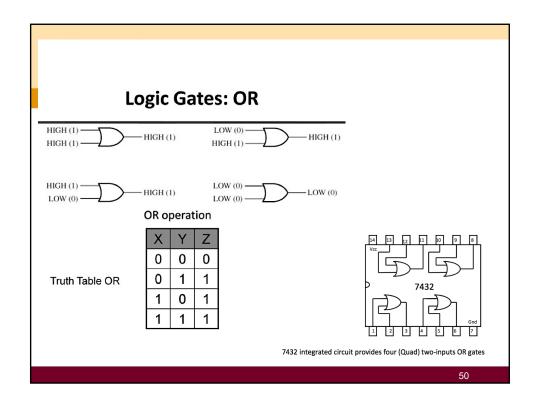


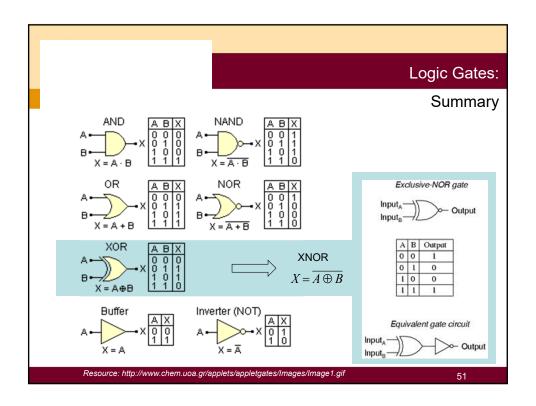


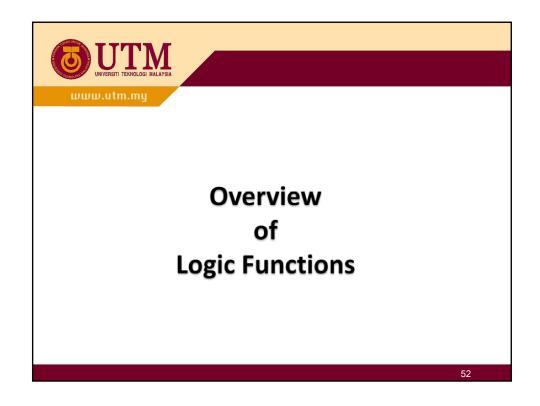












# **Basic Logic Functions**

- Any digital systems has one or more of the following function.
  - ☐ This functions are built from the basic gates.
    - · Comparison Function
    - Arithmetic Functions
    - · Code conversion function
    - · Encoding function
    - · Decoding function
    - · Data selection function
    - · Data storage function
    - · Counting function

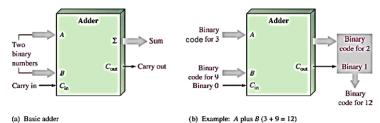
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#### **Comparison Function** Comparator Comparator LOW A > BBinary A > Bcode for 2 Two binary A = BOutputs A = B- LOW numbers Binary code for 5 HIGH A < B(b) Example: A is less than B(2 < 5) as indicated by (a) Basic magnitude comparator the HIGH output (A < B)54

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## **Arithmetic Functions**

Adder



- Subtractor
- Multiplier
- Division

Resource: Floyd, Digital Fundamentals, 10th Edition

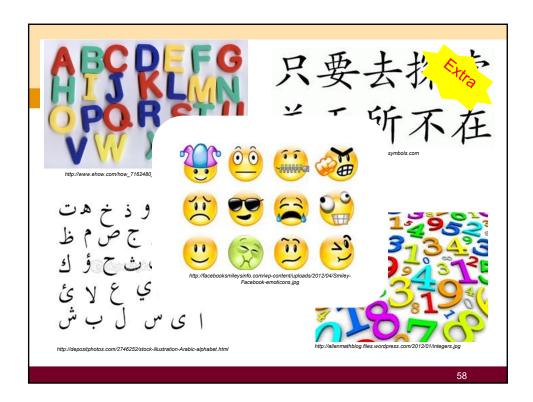
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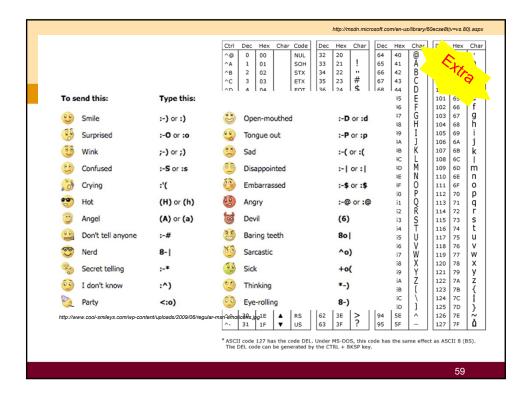
All the other arithmetic operations can be derived from adder:

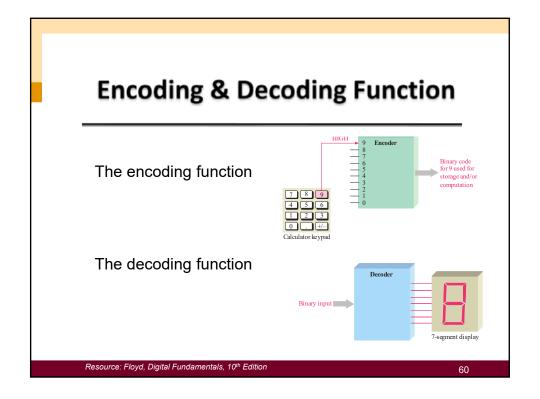
- ☐ Subtraction is and addition of negative number such as A−B = A+(-B)
- Multiplication is a repeated addition such as A\*3=A+A+A
- ☐ Division is a repeated subtraction which is a repeated addition such as 6/3=6-3-3=6+(-3)+-(3)
  - subtract until the remainder = 0
  - total number of subtraction = 2 which is the answer

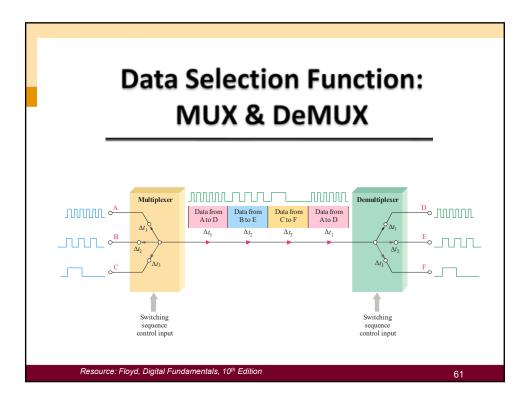
# **Code Conversion Function**

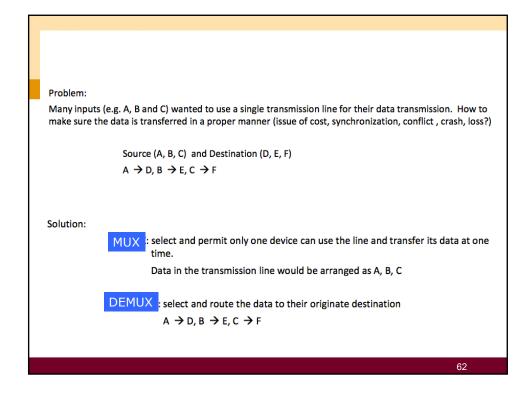
- A code is a set of bits arranged in a unique pattern and used to represent specified information.
  - ∘ Examples : BCD, ASCII
- The usage of codes allow a faster and more efficient data processing.

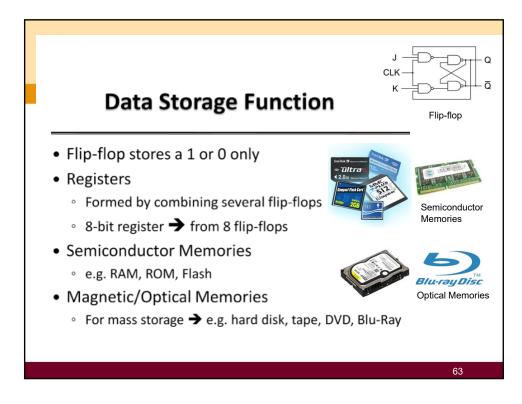


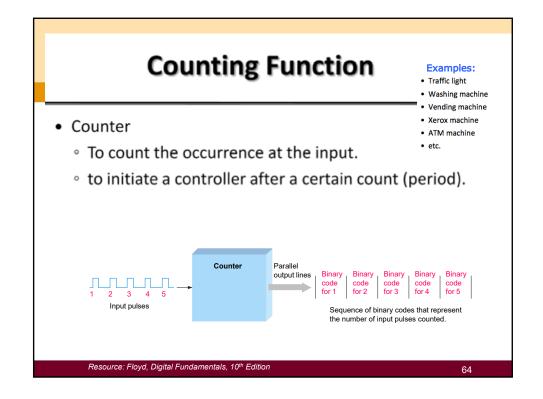












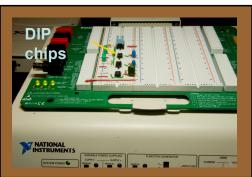


# Fixed-Function Integrated Circuit (IC)

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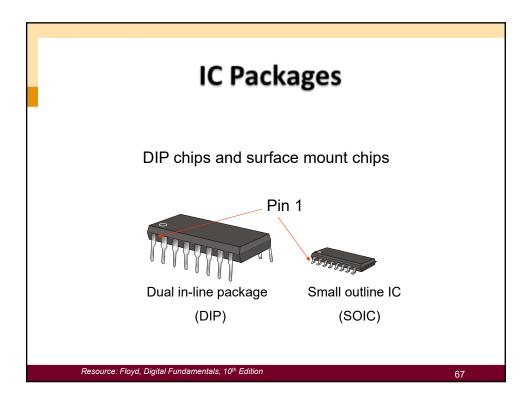
An example of laboratory prototyping is shown. The circuit is wired using DIP chips and tested.

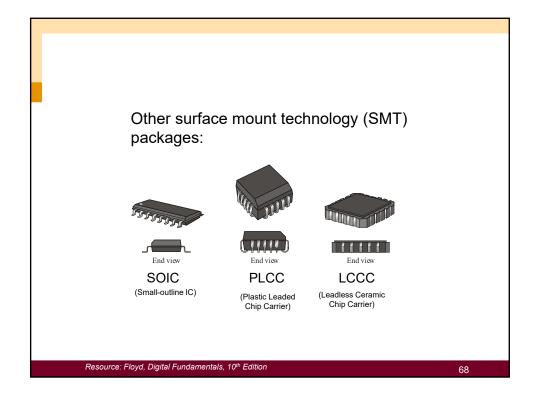
In this case, testing can be done by a computer connected to the system.

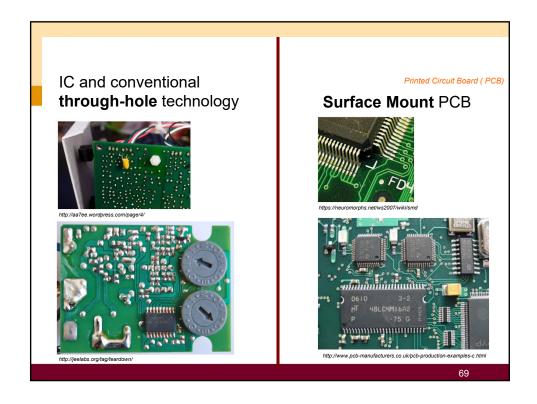


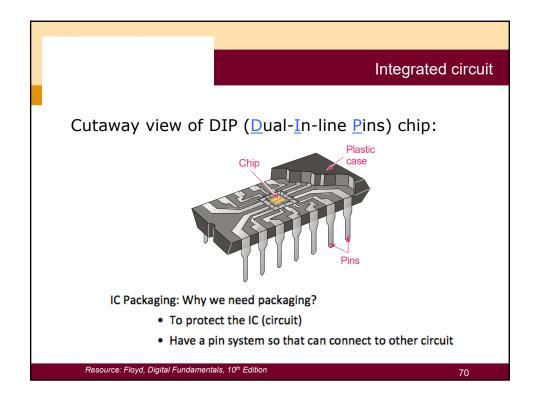
(Dual In-line Package)

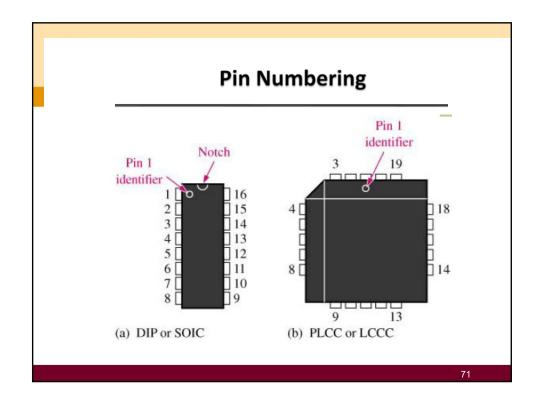
Resource: Floyd, Digital Fundamentals, 10<sup>th</sup> Edition

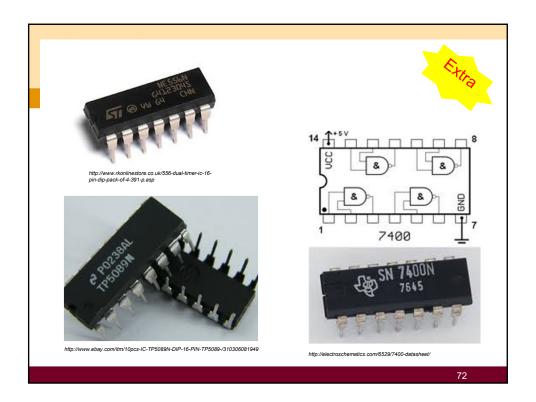












# Complexity Classifications for Fixed-Function ICs

- ☐ Small-scale integration (SSI) have up to 12 gates on a single chip
- ☐ Medium-scale integration (MSI) have from 12-99 gates on a single chip
- □ Large-scale integration (LSI) have from 100-9999 gates on a single chip
- □ Very large-scale integration (VLSI) have from 10,000-99,999 gates on a single chip
- □ Ultra large-scale integration (ULSI)
  have from 100,000 and greater equivalent gates on
  a single chip

Module 1



http://www.visual6502.org/images/263P/SI 263P 8404 chin1 nackage ton ing



http://www.nysemagazine.com/lsicorp

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# **Integrated Circuit Technologies**

# Some examples of IC technologies:

TTL (Transistor-transistor Logic)

• ECL (Emitter-Coupled Logic)

CMOS (Complementary Metal–Oxide–Semiconductor)

NMOS (N-Type Metal—Oxide—Semiconductor)

BiCMOS (Bipolar and Metal–Oxide–Semiconductor)



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# Programmable Logic Devices (PLD)

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#### Overview of PLD

#### ☐ Fixed function

■ A specific logic function is contained in the IC (hardwired) and can never be changed.

#### $\square$ PLD

- Logic function programmed by the user.
  - ■Some, can be reprogrammed many times.

#### ■Advantage

- More logic circuit can be 'stuffed' into much smaller area.
- Certain PLD, design can be changed without rewiring or replacing components.
- ■Can be implemented faster once the required programming language is mastered.

# **Types of PLD**

## 3 major types (SPLD, CPLD, FPGA)

- 1. Simple Programmable Logic Devices (SPLD)
  - · Can replace several fixed-function SSI or MSI
  - · First type available
  - · A few categories
    - PAL (programmable Array Logic)
    - · GAL (Generic Array Logic)
    - PLA (Programmable Logic Array)
    - PROM (Programmable Read-Only memory)

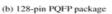
# Types of PLD: CPLD

- 2. Complex Programmable Logic Devices (CPLD)
  - Much higher capacity than SPLD (2-64 SPLD)
    - · More complex logic circuits can be programmed
    - Typically in 44 160 pin package











Resource: http://upload.wikimedia.org/wikipedia/commons/thumb/a/a3/ Altera MAX 7128 2500 gate CPLD.jpg/300px-Altera MAX 7128 2500 gate CPLD.jpg

# Types of PLD: FPGA

- 3. Field-Programmable Gate Arrays (FPGA)
  - Different internal organization than SPLD and CPLD
  - Greatest logic capacity
    - Consist of 64- thousands logic block (logic gate groups)
  - Classes
    - Fine grain (smaller logic block)
    - Coarse grain (large logic block)

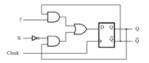


Resource: http://upload.wikimedia.org/wikipedia/commons/thumb/fifa/ Altera\_StratixIVGX\_FPGA.jpg/300px-Altera\_StratixIVGX\_FPGA.jpg

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# **PLD Programming**

- Logic circuit entered using 2 basic method
  - Graphical entry
    - · schematic diagram



- Text-based entry (language based entry)
  - Using Hardware Description Language (HDL)
    - Eg . ABEL, CUPL, WinCUPL
    - Becoming widely used especially for CPLD and FPGA
      - VHDL
      - Verilog



Resource: Floyd, Digital Fundamentals, 10<sup>th</sup> Edition