



SECP 1013 DISCRETE STRUCTURE

TUTORIAL 4

LECTURER: Dr Razana Alwee

SUBMITTED BY:

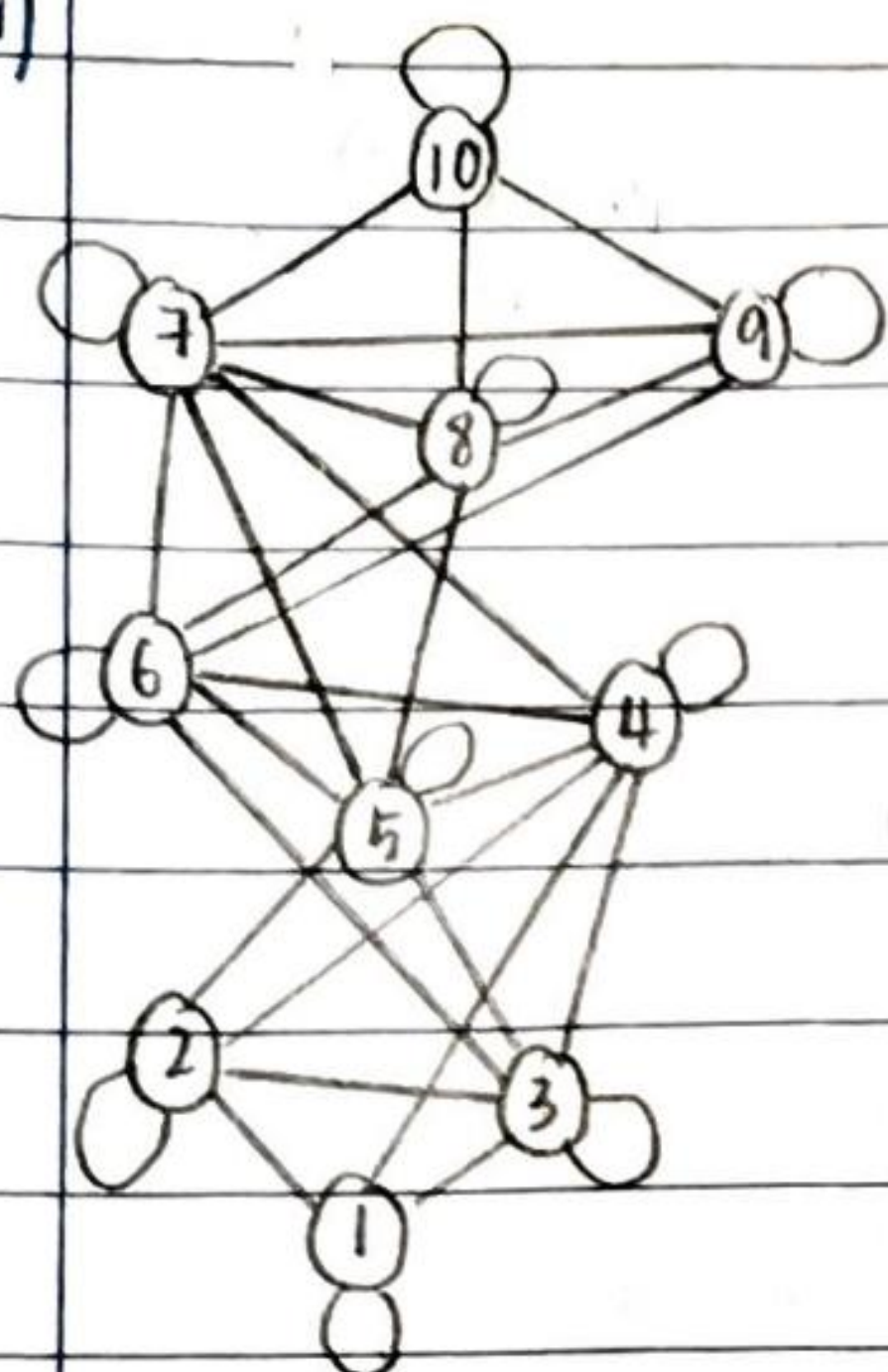
T1

Adam Mustaqim Bin Azmi (A20EC0235)

Chong Kah Wei (A20EC0027)

Muhammad Aiman Bin Abdul Razak (A20EC0082)

1)



Edge Endpoints

 e_1 $\{10, 10\}$ e_2 $\{9, 9\}$ e_3 $\{8, 8\}$ e_4 $\{7, 7\}$ e_5 $\{6, 6\}$ e_6 $\{5, 5\}$ e_7 $\{4, 4\}$ e_8 $\{3, 3\}$ e_9 $\{2, 2\}$ e_{10} $\{1, 1\}$

Edge

Endpoints

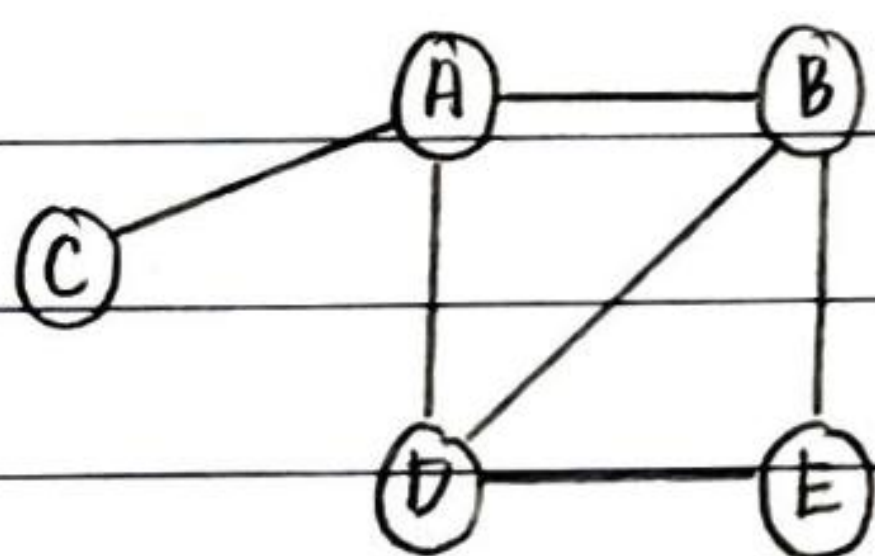
 e_{11} $\{10, 9\}$ e_{12} $\{10, 8\}$ e_{13} $\{10, 7\}$ e_{14} $\{9, 8\}$ e_{15} $\{9, 7\}$ e_{16} $\{9, 6\}$ e_{17} $\{8, 7\}$ e_{18} $\{8, 6\}$ e_{19} $\{8, 5\}$ e_{20} $\{7, 6\}$ e_{21} $\{7, 5\}$ e_{22} $\{7, 4\}$

Edge

Endpoints

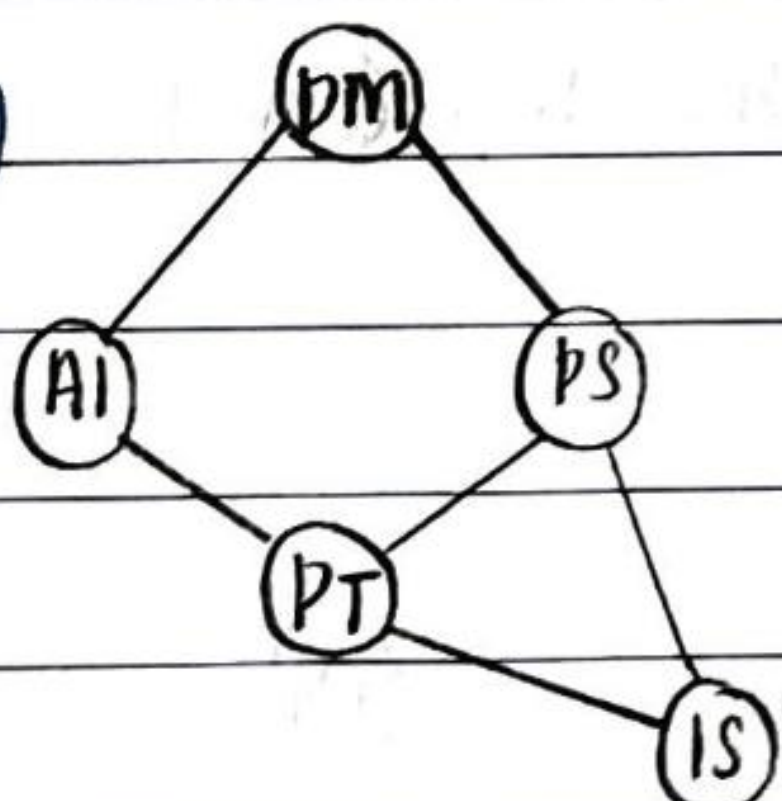
 e_{23} $\{6, 5\}$ e_{24} $\{6, 4\}$ e_{25} $\{6, 3\}$ e_{26} $\{5, 4\}$ e_{27} $\{5, 3\}$ e_{28} $\{5, 2\}$ e_{29} $\{4, 3\}$ e_{30} $\{4, 2\}$ e_{31} $\{4, 1\}$ e_{32} $\{3, 2\}$ e_{33} $\{3, 1\}$ e_{34} $\{2, 1\}$ $\therefore e(G) = 34$ edges

2) a)



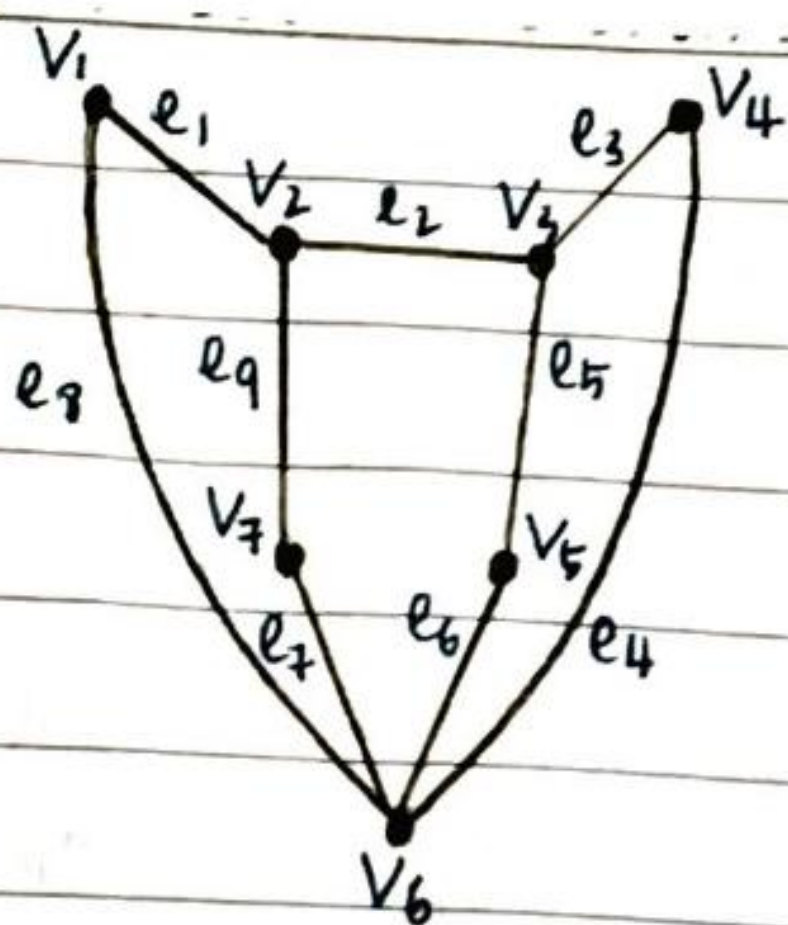
$$A_G = \begin{matrix} & \begin{matrix} A & B & C & D & E \end{matrix} \\ \begin{matrix} A \\ B \\ C \\ D \\ E \end{matrix} & \begin{bmatrix} 0 & 1 & 1 & 1 & 0 \\ 1 & 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 & 0 \end{bmatrix} \end{matrix}$$

b)



$$A_G = \begin{matrix} & \begin{matrix} bm & PT & AI & PS & IS \end{matrix} \\ \begin{matrix} bm \\ PT \\ AI \\ PS \\ IS \end{matrix} & \begin{bmatrix} 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 & 1 \\ 1 & 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 & 0 \end{bmatrix} \end{matrix}$$

3)



4) G :

$$A_G = \begin{matrix} & \begin{matrix} V_1 & V_2 & V_3 & V_4 \end{matrix} \\ \begin{matrix} V_1 \\ V_2 \\ V_3 \\ V_4 \end{matrix} & \begin{bmatrix} 1 & 0 & 2 & 0 \\ 0 & 0 & 1 & 0 \\ 2 & 1 & 0 & 2 \\ 0 & 0 & 2 & 0 \end{bmatrix} \end{matrix}$$

$$I_G = \begin{matrix} & \begin{matrix} e_1 & e_2 & e_3 & e_4 & e_5 & e_6 \end{matrix} \\ \begin{matrix} V_1 \\ V_2 \\ V_3 \\ V_4 \end{matrix} & \begin{bmatrix} 2 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 & 1 & 1 \end{bmatrix} \end{matrix}$$

H :

$$A_H = \begin{matrix} & \begin{matrix} V_1 & V_2 & V_3 & V_4 \end{matrix} \\ \begin{matrix} V_1 \\ V_2 \\ V_3 \\ V_4 \end{matrix} & \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 2 \\ 0 & 1 & 1 & 0 \\ 0 & 2 & 0 & 0 \end{bmatrix} \end{matrix}$$

$$I_H = \begin{matrix} & \begin{matrix} e_1 & e_2 & e_3 & e_4 & e_5 & e_6 \end{matrix} \\ \begin{matrix} V_1 \\ V_2 \\ V_3 \\ V_4 \end{matrix} & \begin{bmatrix} 2 & 0 & 0 & 0 & 0 & 0 \\ 0 & 2 & 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 & 2 \\ 0 & 0 & 1 & 1 & 0 & 0 \end{bmatrix} \end{matrix}$$

5) a) No. of vertices $G_1 = 5$, $G_2 = 5$

No of edges $G_1 = 5$, $G_2 = 5$

$\text{Deg}(V_1) = 2$, $\text{Deg}(V_2) = 2$, $\text{Deg}(V_3) = 3$, $\text{Deg}(V_4) = 2$, $\text{Deg}(V_5) = 1$

$\text{Deg}(u_1) = 1$, $\text{Deg}(u_2) = 3$, $\text{Deg}(u_3) = 2$, $\text{Deg}(u_4) = 2$, $\text{Deg}(u_5) = 2$

Both G_1 and G_2 have 1 vertex with 1 degree, 3 vertices with 2 degree and 1 vertices with 3 degree.

$f(V_1) = u_5$, $f(V_2) = u_3$, $f(V_3) = u_2$, $f(V_4) = u_4$, $f(V_5) = u_1$

Adjacency Matrix, A_{G_1}

$$= \begin{matrix} & \begin{matrix} V_1 & V_2 & V_3 & V_4 & V_5 \end{matrix} \\ \begin{matrix} V_1 \\ V_2 \\ V_3 \\ V_4 \\ V_5 \end{matrix} & \begin{bmatrix} 0 & 1 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 1 & 1 \\ 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \end{bmatrix} \end{matrix}$$

Adjacency Matrix, A_{G_2}

$$= \begin{matrix} & \begin{matrix} u_5 & u_3 & u_2 & u_4 & u_1 \end{matrix} \\ \begin{matrix} u_5 \\ u_3 \\ u_2 \\ u_4 \\ u_1 \end{matrix} & \begin{bmatrix} 0 & 1 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 1 & 1 \\ 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \end{bmatrix} \end{matrix}$$

$\therefore G_1$ and G_2 are isomorphic.

b) Number of vertices $H_1 = 5$, $H_2 = 5$

Number of edges $H_1 = 6$, $H_2 = 6$

$\text{Deg}(a_1) = 1$, $\text{Deg}(a_2) = 1$, $\text{Deg}(a_3) = 3$, $\text{Deg}(a_4) = 2$, $\text{Deg}(a_5) = 4$

$\text{Deg}(x_1) = 3$, $\text{Deg}(x_2) = 1$, $\text{Deg}(x_3) = 3$, $\text{Deg}(x_4) = 3$, $\text{Deg}(x_5) = 2$

$\therefore$ The graphs are not isomorphic because they do not have same degrees for corresponding vertices.

When $f: H_1 \rightarrow H_2$, it cannot be achieved.

6a) $(v_0, e_1, v_1, e_{10}, v_5, e_9, v_2, e_2, v_1)$ is a trail from v_0 to v_1 since it is a walk from v_0 to v_1 that does not contain repeated edge.

b) $(v_4, e_7, v_2, e_9, v_5, e_{10}, v_1, e_3, v_2, e_9, v_5)$ is just a walk from v_4 to v_5 .

c) v_2 is a trivial walk.

d) $(v_5, e_9, v_2, e_4, v_3, e_5, v_4, e_6, v_4, e_8, v_5)$ is a circuit / cycle since it is a closed walk that contains at least one edge and does not contain a repeated edge.

e) $(v_2, e_4, v_3, e_5, v_4, e_8, v_5, e_9, v_2, e_7, v_4, e_5, v_3, e_4, v_2)$ is a closed walk since it starts and ends at the same vertex.

f) $(v_3, e_5, v_4, e_8, v_5, e_{10}, v_1, e_3, v_2)$ is a path from v_3 to v_2 since it is a trail that does not contain a repeated vertex.

7a) $(v_1, e_1, v_2, e_2, v_3, e_5, v_4)$

$(v_1, e_1, v_2, e_3, v_3, e_5, v_4)$

$(v_1, e_1, v_2, e_4, v_3, e_5, v_4)$

3 paths

b) $(v_1, e_1, v_2, e_2, v_3, e_4, v_2, e_3, v_3, e_5, v_4)$

$(v_1, e_1, v_2, e_3, v_3, e_4, v_2, e_2, v_3, e_5, v_4)$

$(v_1, e_1, v_2, e_4, v_3, e_2, v_2, e_3, v_3, e_5, v_4)$

$(v_1, e_1, v_2, e_2, v_3, e_3, v_2, e_4, v_3, e_5, v_4)$

4 trails

$(v_1, e_1, v_2, e_3, v_3, e_2, v_2, e_4, v_3, e_5, v_4)$

$(v_1, e_1, v_2, e_4, v_3, e_3, v_2, e_2, v_3, e_5, v_4)$

c) There is infinity walk from V_1 to V_4 .

8) (a)

Vertex	V_1	V_2	V_3	V_4	V_5
Degree	2	4	2	4	4

(b)

Vertex	V_0	V_1	V_2	V_3	V_4	V_5	V_6	V_7	V_8	V_9
Degree	2	4	2	2	2	4	2	3	3	3

(a) has Euler circuit since all the vertices have even degree.

For example, $V_1, e_1, V_2, e_2, V_5, e_7, V_4, e_6, V_5, e_3, V_2, e_4, V_3, e_5, V_4, e_8, V_1$

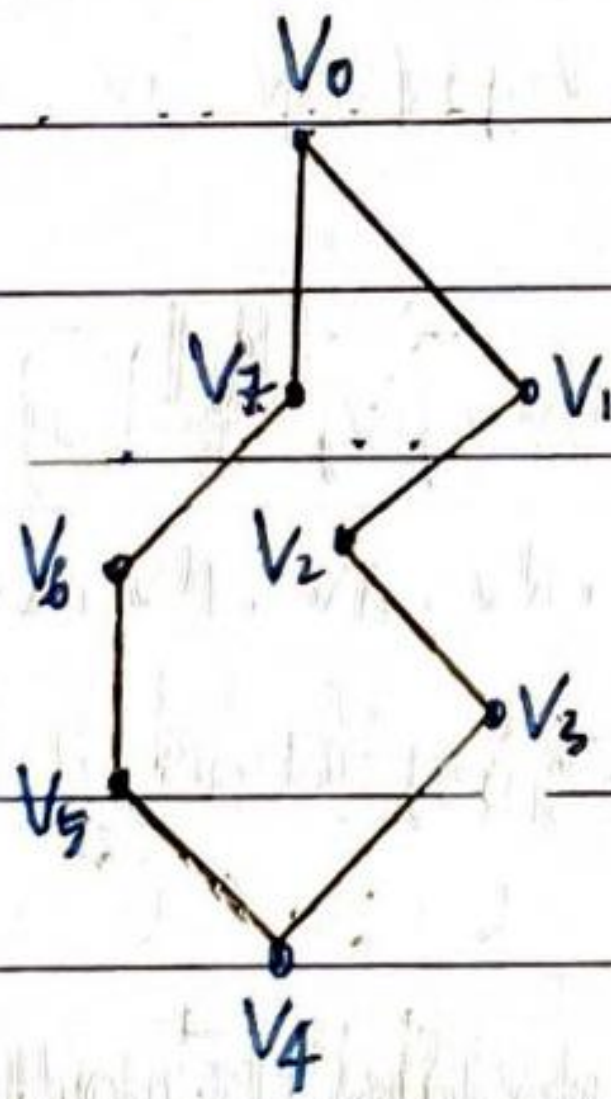
(b) has no Euler circuit since the vertices V_7, V_8 and V_9 have odd degrees.

9) (a) has Euler path.

Euler path = $U, V_1, V_0, V_7, U, V_2, V_4, V_4, V_2, V_6, V_4, W, V_6, V_5, W$

(b) has no Euler path.

10) (a) has Hamiltonian circuit, which is $V_2, V_1, V_7, V_0, V_6, V_5, V_4, V_3, V_2$.



(b) does not have Hamiltonian Circuit.

$$11) \quad n = \frac{m \cdot l - 1}{m - 1}$$

$$l = \frac{n(m-1)+1}{m}$$

$$= \frac{100(3-1)+1}{3}$$

$$= 67$$

12) a) {a}

b) {a, b, e, g, n, d, h, j}

c) {k, l, m, f, r, s, c, o, i, p, q}

d) {r, s}

e) {b}

f) {l, m}

g) {a, d, j}

h) {e, k, l, m, f, g, n, r, s}

13) preorder

a, b, e, k, l, m, f, g, n, r, s, c, d, h, o, i, j, p, q

inorder

k, e, l, m, f, b, r, n, s, g, c, a, o, h, d, i, p, j, q

postorder

k, l, m, e, f, r, s, n, g, b, c, a, o, h, i, d, p, q, j

14) AB 1 DH 6

GH 1 DG 7

BC 2 DE 7

AF 3 EH 8

BF 4 FG 8

CD 4

BG 5

CG 6

AB 1

GH 1

BC 2

AF 3

CD 4

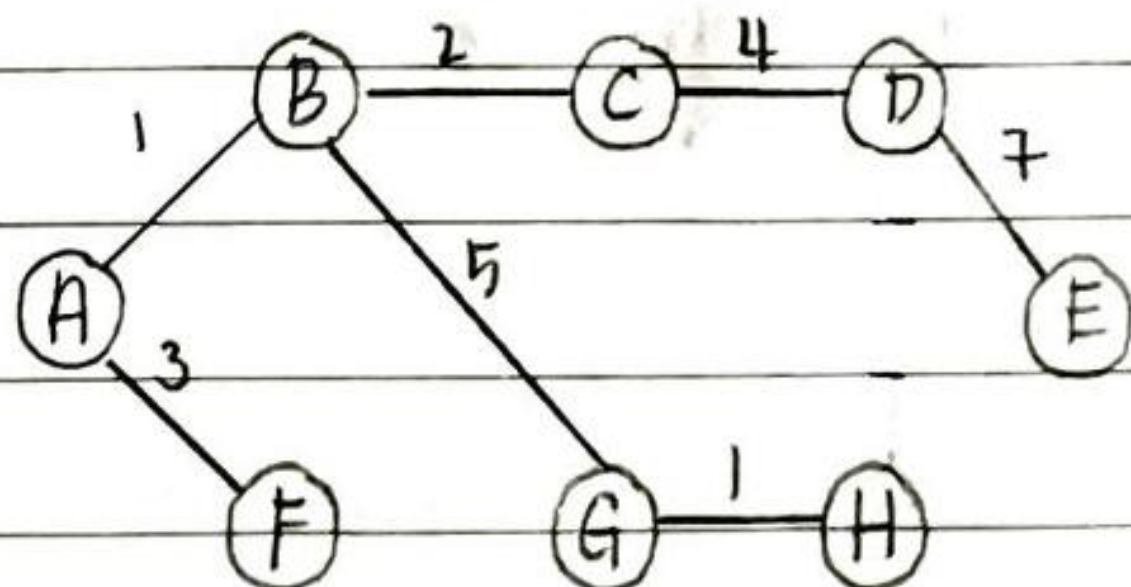
BG 5

DE 7

Weight of subgraph:

$$1+1+2+3+4+5+7$$

$$= 23$$



15)	i	S	N	L(M)	L(N)	L(O)	L(P)	L(Q)	L(R)	L(S)	L(T)	No.
	0	{}	{M, N, O, P, Q, R, S, T}	0	∞	∞	∞	∞	∞	∞	∞	
	1	{M}	{N, O, P, Q, R, S, T}	0	4	∞	2	∞	5	∞	∞	
	2	{M, P}	{N, O, Q, R, S, T}	0	4	∞	2	6	5	5	∞	
	3	{M, N, P}	{O, Q, R, S, T}	0	4	10	2	6	5	5	∞	
	4	{M, N, P, R}	{O, Q, S, T}	0	4	7	2	6	5	5	6	
	5	{M, N, P, R, S}	{O, Q, T}	0	4	7	2	6	5	5	6	
	6	{M, N, P, R, S, T}	{O, Q}	0	4	7	2	6	5	5	6	

Minimum distance = 6

Shortest path from M to T is M-R-T.

Jumlah