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SCSR1013 DIGITAL LOGIC

MODULE 1: INTRODUCTORY CONCEPTS

2019/2020-1

FACULTY OF COMPUTING



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MODULE 1: DIGITAL LOGIC OVERVIEW

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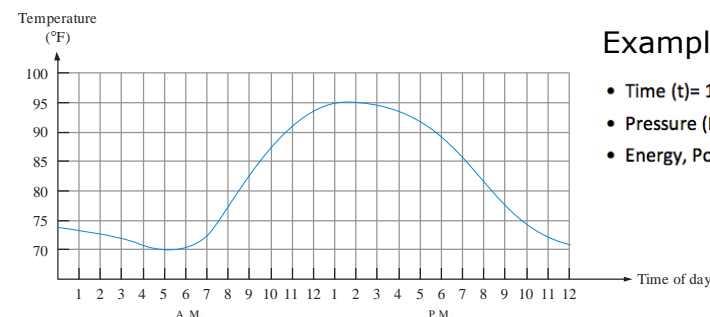


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Digital and Analog Quantities

Analog quantities

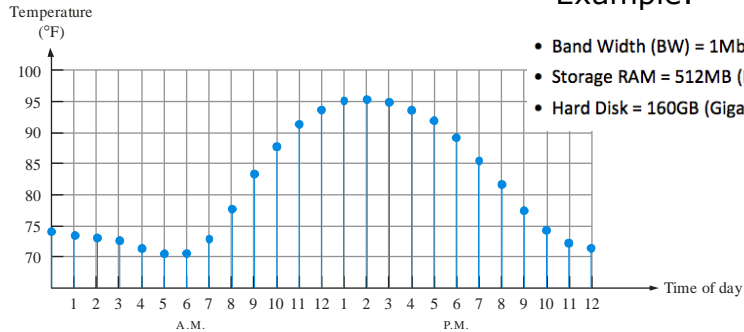
- Most natural quantities that we see are **analog** and vary continuously.
- Analog systems can generally handle higher power than digital systems.



Example:

- Time (t) = 10.16s (second)
- Pressure (P) = 220.10KPa (Kilo Pascal)
- Energy, Power = 100.5KW (Kilo Watts)

Example:



- Band Width (BW) = 1Mbps (Mega Bits Per Second)
- Storage RAM = 512MB (Mega Byte)
- Hard Disk = 160GB (Giga Byte)

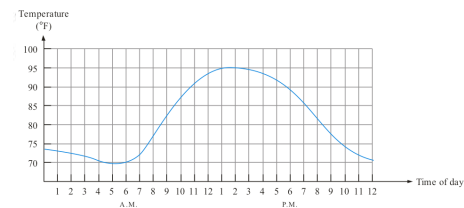
- Digital systems can **process**, **store**, and **transmit** data more efficiently but can only assign discrete values (**discontinuous**) to each point.

Resource: Floyd, Digital Fundamentals, 10th Edition

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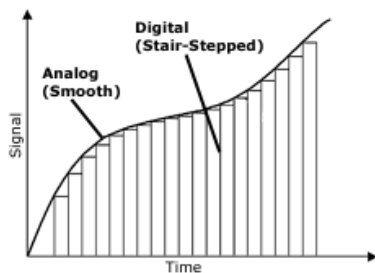
Analog

- Use base 10 (decimal)
- Represented by 10 different level: 0, 1, 2, 3, 4, 5, 6, 7, 8, and 9.
- Analog system: A combination of devices that manipulate values represented in analog form

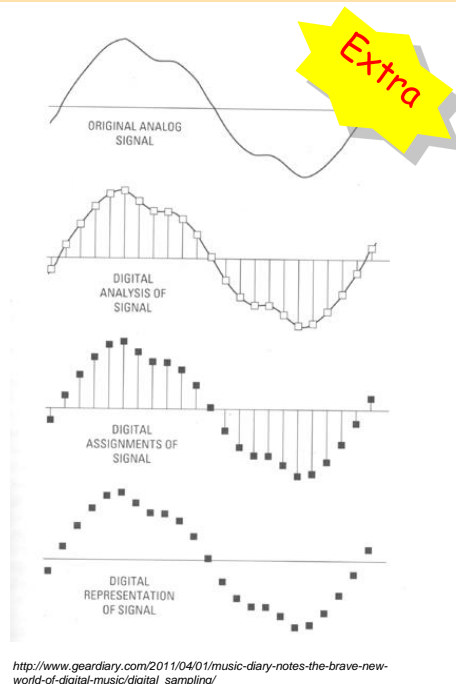


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Example of sampling analog-to-digital (frequency at least 2 times higher than analog)

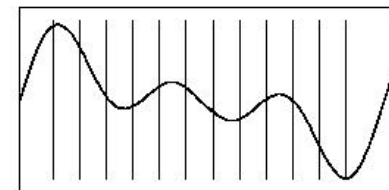


<http://www.blazeaudio.com/howto/bg-digital.html>

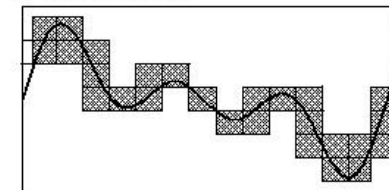


http://www.geardiary.com/2011/04/01/music-diary-notes-the-brave-new-world-of-digital-music/digital_sampling/

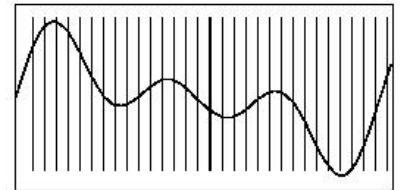
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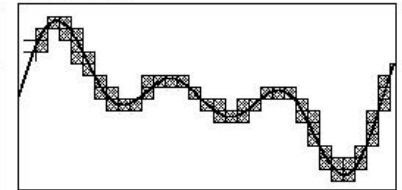
Lower sample rates take fewer snapshots of the waveform



resulting in a rough recreation of the waveform.



faster sample rates take more snapshots....



resulting in a smoother and more detailed recreation of the waveform.

<http://musicandcomputers306.blogspot.com/2010/10/waveforms-ad-conversion-sampling.html>

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Extra

Self-Test: Which of the following belong to analog system?



(a)



(b)



(c)



(d)



(e)



(f)

Resource: Google searched

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Extra

Answer



(a)



(c)



(e)

Resource: Google searched

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Extra

Example: Analog systems



Resource: Google searched

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Extra

Example: Digital systems



Resource: Google searched

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- Digital technology is relatively new compared to analog technology, but a lot of analog systems has been changed to a digital systems, Examples:

- Computers
- Manufacturing systems
- Medical Science
- Transportation
- Entertainment
- Telecommunications



*DSL-2320B (ADSL Modem)

Resource: <http://www.wirelessnetworkproducts.com/dsl-2320b.aspx>

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Exercise: Match the picture to which digital application system it belong to.



(b)



(e)



(a)

- (a) Computers
- (b) Manufacturing systems
- (c) Medical Science
- (d) Transportation
- (e) Entertainment
- (f) Telecommunications



(d)



(f)



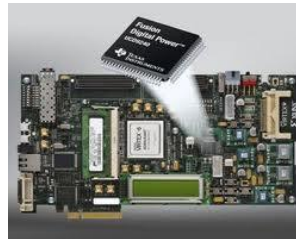
(c)

Resource: <http://www.wirelessnetworkproducts.com/dsl-2320b.aspx>

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The Digital Advantages

- Ease of design
- Ease of storage
- Accuracy and precision are easier to maintain
- Programmable operation
- Less affected by noise
- Ease of fabrication on IC chips



□ Thus, the digital systems is more efficient and reliable for:

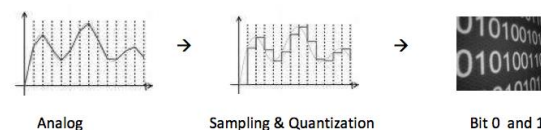
- Data Processing
- Data Transmission
- Data Storage

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Digital Disadvantages

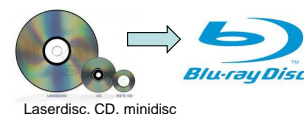
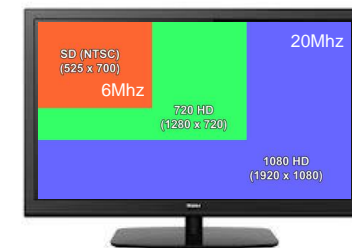
- Greater bandwidth
- Sampling error

Sampling Error (Quantization Error): is derived from Analog to Digital Conversion Process:



- Compatibility with existing analog systems
- Short product half life

http://www.tvjuneau.com/images/HDTV-Resolutions_Full.jpg

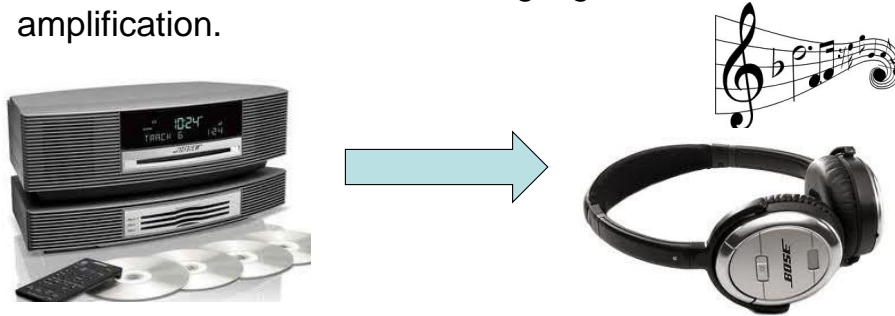


Laserdisc, CD, minidisc

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Analog and Digital Systems

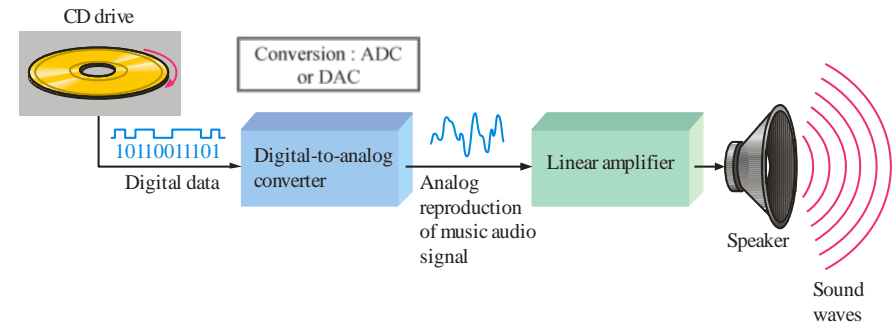
- Many systems use a **mix** of analog and digital electronics to take advantage of each technology.
- A typical CD player accepts digital data from the CD drive and converts it to an analog signal for amplification.



<http://www.it-echo.com/2009/11/14/bose-wave-music-system-and-multi-cd-changer-bundle.html>
<http://cdn-static.zdnet.com/story/6/1/18/006128/31929466-2-440-overview-1.gif>

Resource: Floyd, Digital Fundamentals, 10th Edition

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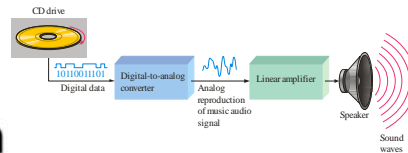


1. Convert digital sound (CD) to analog
2. Process (amplify) the analog information
3. Convert the analog signal to sound

Resource: Floyd, Digital Fundamentals, 10th Edition

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Hybrid System



- The audio CD is a typical hybrid (Analog & Digital) system.
 - Analog sound is converted into analog voltage using a microphone.
 - Analog voltage is changed into digital through an ADC in the recorder.
 - Digital information is stored on the CD .
 - At playback the digital information is changed into analog by a DAC in the CD player.
 - The analog voltage is amplified and used to drive a speaker that produces the original analog sound.

Conversion:



<http://www.idt.com/products/data-converters>

Analog to Digital Converter (ADC):

- Convert analog signal into digital signal using process such as sampling, quantization process and digital conversion.
- Error will occur during the sampling and quantization, hence loss of information can happen.

Digital to Analog Converter (DAC):

- Needed if the speaker is using analog system.
- Need to convert the digital data to analog signal in order for the speaker works properly and the sound can heard by human.



<http://thesoundviewstudio.com/audio-rentals.html>

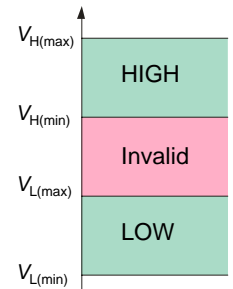
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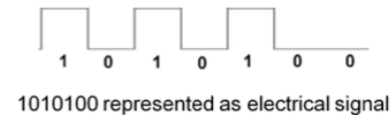
Digits, Logic Levels and Digital Waveform

Digital electronics uses circuits that have two states, which are represented by two different voltage levels:

- HIGH (bit 1)
- LOW (bit 0)



A bit can have the value of either a 0 or a 1, depending on if the voltage is **HIGH** or **LOW**.

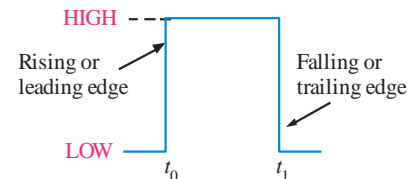


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 Resource: Floyd, Digital Fundamentals, 10th Edition

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- **Digital waveforms** change between the **LOW** and **HIGH** levels.
- A positive going pulse is one that goes from a normally **LOW** logic level to a **HIGH** level and then back again.
- **Digital waveforms** are made up of a series of pulses.

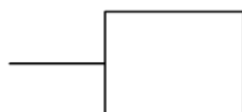


(a) Positive-going pulse

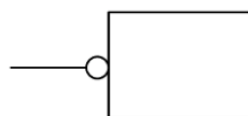
**Positive Logic
(active high)**

High = 1 (Bit 1)
 Low = 0 (Bit 0)

Symbols to show the input state of “active high” and “active low”:



“active high”



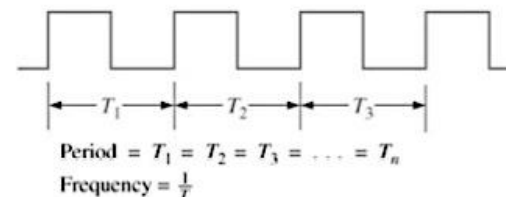
“active low”

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• Two type of squarewave

◦ Periodic

- The signal keep on repeating after a period of time



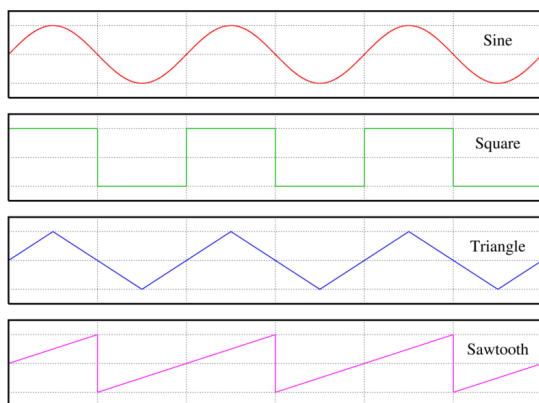
◦ Non-Periodic / Aperiodic

- Doesn't have a period



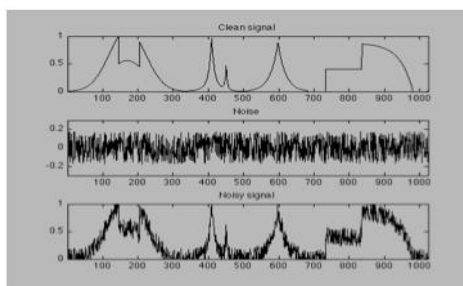
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Periodic signal



<http://commons.wikimedia.org/wiki/File:Waveforms.png>

Aperiodic signal



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Periodic Signal Parameter

- Frequency (f) is the rate at which the signal repeat itself at a fixed interval. Is measured in cycles per second or Hertz (Hz)

$$f = \frac{1}{T} \text{ Hz}$$

- Period (T) is the time from the edge of one pulse to the corresponding edge of the next pulse. Is measured in second

$$T = \frac{1}{f} \text{ seconds}$$

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Example:

- clock frequency : $f = 100\text{Hz}$,
so, period : $T = 1/100\text{Hz} = 0.01\text{s} = 10 \times 10^{-3} = 10\text{ ms}$

$$\begin{array}{l} \text{s} \rightarrow \text{ms} (\times 10^3) \\ \text{ms} \rightarrow \text{s} (\times 10^{-3}) \end{array}$$

Some examples of periodic signal display on the oscilloscope:



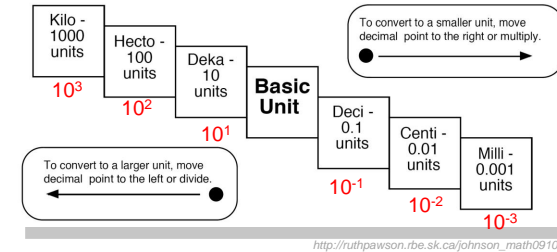
(a) Square waveform



(b) Sinusoid waveform

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Metric Conversion Chart



http://ruthpawson.rbe.sk.ca/johnson_math0910

Unit Conversion

- Kilo (K) = 10^3
- Mega (M) = 10^6
- Giga (G) = 10^9
- Tera (T) = 10^{12}
- Mili (m) = 10^{-3}
- Micro (μ) = 10^{-6}
- Nano (n) = 10^{-9}
- Piko (p) = 10^{-12}

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Example : $f = 100\text{KHz}$, So
 $T = 1/f$
 $= 1/(100 \times 10^3\text{Hz})$
 $= 0.01 \times 10^{-3}\text{s}$
 $= 0.01\text{ms}$
 $= 10\mu\text{s}$

$$\begin{aligned} &= (0.01 \times 10^{-3})\text{s} \times 10^3 \\ &= (0.01 \times 10^{-3+3})\text{ms} \\ &= (0.01 \times 10^0)\text{ms} \\ &= 0.01\text{ms} \end{aligned}$$

$$\begin{aligned} &= (0.01 \times 10^{-3})\text{s} \times 10^6 \\ &= (0.01 \times 10^{-3+6})\mu\text{s} \\ &= (0.01 \times 10^3)\mu\text{s} \\ &= 10\mu\text{s} \end{aligned}$$

- Mili (m) = 10^{-3}
- Micro (μ) = 10^{-6}
- Nano (n) = 10^{-9}
- Piko (p) = 10^{-12}

Exercise 1.1 : Calculate the frequency of signals if time period are given as the following:

- $10\text{ms} = \underline{\hspace{2cm}}\text{Hz}$
- $100\text{ms} = \underline{\hspace{2cm}}\text{KHz}$
- $100\text{ns} = \underline{\hspace{2cm}}\text{MHz}$
- $1000\text{ps} = \underline{\hspace{2cm}}\text{GHz}$

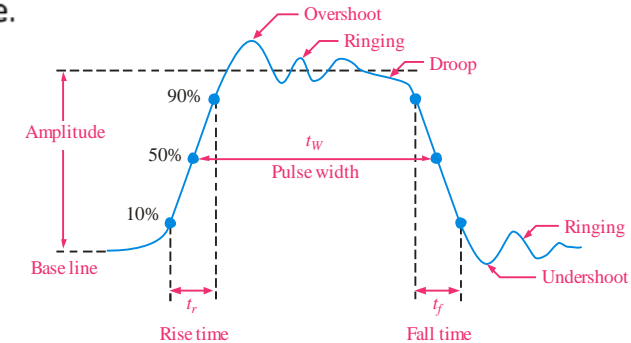
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Exercise 1.2 : Calculate the time period of signals if the frequencies are given as the following:

- a) $1000\text{KHz} = \underline{\hspace{2cm}} \text{ms}$
- b) $100\text{MHz} = \underline{\hspace{2cm}} \text{ns}$
- c) $1000\text{GHz} = \underline{\hspace{2cm}} \text{ps}$
- d) $100\text{THz} = \underline{\hspace{2cm}} \text{ps}$

- Pulse is a rapid, transient change in the amplitude of a signal from a baseline value to a higher or lower value, followed by a rapid return to the baseline value.
- Pulse width (t_w): A measure of the duration of the pulse.
- Rise time and fall time is a measure of how fast the pulse change.



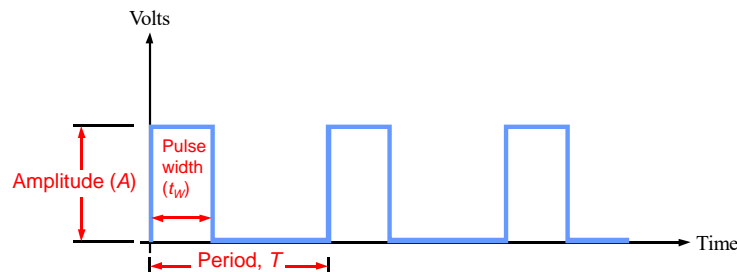
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Resource: Floyd, Digital Fundamentals, 10th Edition

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Repetitive Pulse Waveform

- In addition to frequency and period, repetitive pulse waveforms are described by the **amplitude (A)**, **pulse width (t_w)** and **duty cycle**.
- Duty cycle is the ratio of t_w to T .



Duty Cycle

- Duty cycle is the fraction of time that a system is in an "active" state (operated), defined as

$$\text{Duty cycle} = (t_w/T)100\%$$



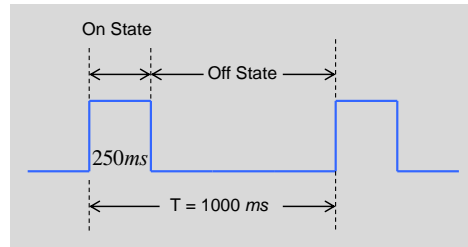
Example : a periodic digital waveform has a pulse width (t_w) 1ms and period time (T) 10ms, calculate duty cycle?

$$\text{Duty cycle} = 1\text{ms}/10\text{ms} * 100\% = 10\%$$

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Exercise 1.3: Given the duration or period of a system is 1000ms, determine the *on state* and *off state* of the system that operate with the ratio of duty cycle is 25%. Show your works.



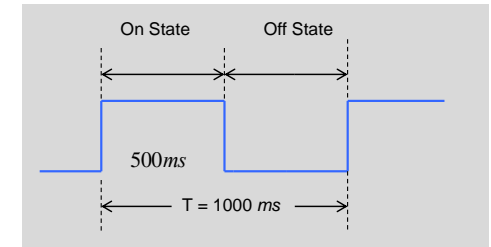
Solution 1.3:

Duty cycle → on state

$$= 25\% \cdot 1000ms = \frac{25}{100} \cdot 1000ms = \frac{1}{4} \cdot 1000ms = 250ms$$

$$\text{Off state} : = 1000ms - 250ms = 750ms$$

Exercise 1.4: Given the duration or period of a system is 1000ms, determine the *on state* and *off state* of the system that operate with the ratio of duty cycle is 50%. Show your works.



Solution 1.4:

Duty cycle → on state

$$= 50\% \cdot 1000ms = \frac{50}{100} \cdot 1000ms = \frac{1}{2} \cdot 1000ms = 500ms$$

$$\text{Off state} : = 1000ms - 500ms = 500ms$$

Exercise 1.5: Given the *duty cycles* of a system is 40% for a duration of a system is 500ms.

- Calculate the pulse width of the system.
- Determine the *off state* of the system that operate with the ratio of duty cycle.

Show your works.

Solution 1.5:

$$\text{a) } \text{DutyCycle} = \left(\frac{t_w}{T}\right)100$$

$$40 = \left(\frac{t_w}{500}\right)100$$

$$t_w = \frac{40(500)}{100} = 200s$$

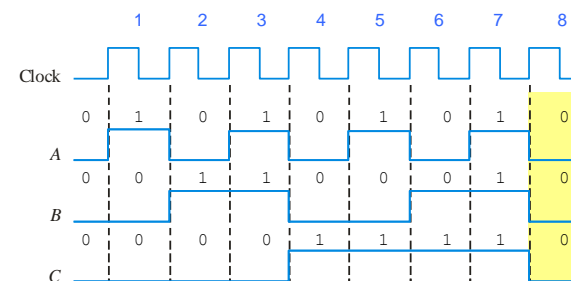
$$\text{b) } \text{Period} = 500ms$$

$$\text{OnState} = t_w = 200ms$$

$$\setminus 500 - 200 = 300ms$$

Timing diagram

A timing diagram is used to show the relationship between two or more digital waveforms,

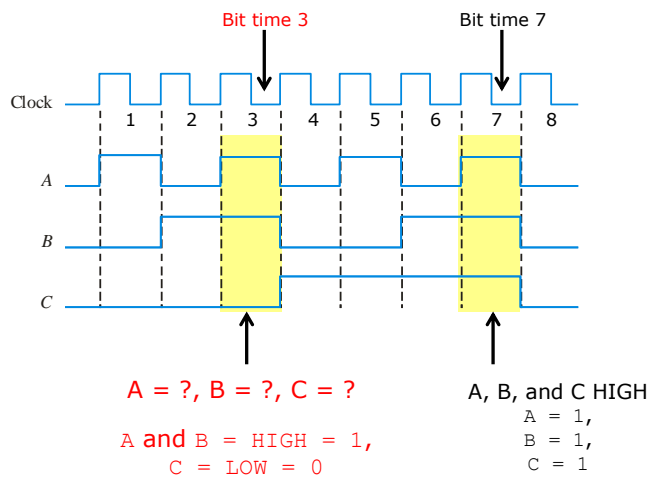


At time 8, all A, B, and C **LOW**

A diagram like this can be observed directly on a logic analyzer.



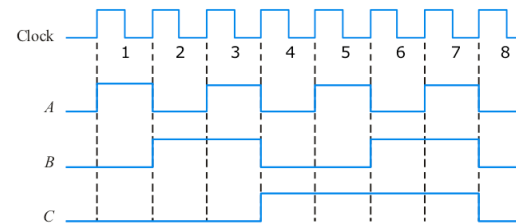
Example: Timing Diagram



Resource: Floyd, Digital Fundamentals, 10th Edition

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Example: Timing Diagram



Clock (↑)	Input		Output
	A	B	C
1	1	0	0
2	0	1	0
3	1	1	0
4	0	0	1
5	1	0	1
6	0	1	1
7	1	1	1
8	0	0	0

Exercise: Complete the truth table.

Resource: Floyd, Digital Fundamentals, 10th Edition

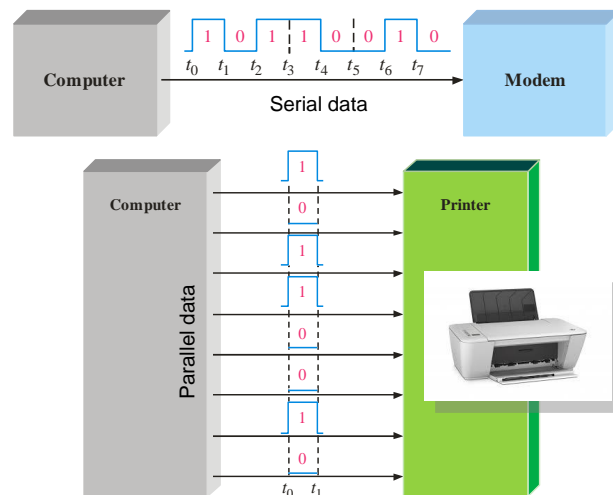
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Data Transfer



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Data can be transmitted by either **serial** transfer or **parallel** transfer.



Resource: Floyd, Digital Fundamentals, 10th Edition

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Introduction to Logic Operations

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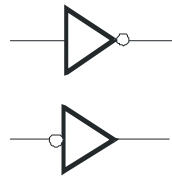
AND True only if **all** input conditions are true.



OR True only if **one or more** input conditions are true.



NOT Indicates the **opposite** condition (inverter).



Logic Gates: NOT

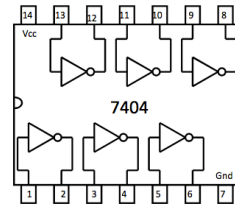


NOT operation

Truth table shows the relationship between output and the input.

Truth Table for NOT

X	Z
0	1
1	0



7404 IC six inverters

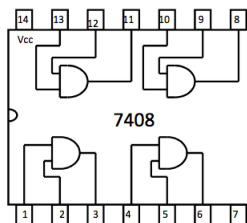
Logic Gates: AND



AND operation

Truth Table AND

X	Y	Z
0	0	0
0	1	0
1	0	0
1	1	1



7408 IC four (Quad) AND gates

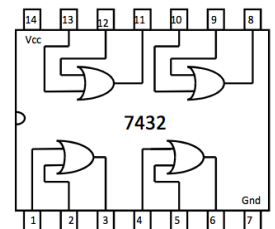
Logic Gates: OR



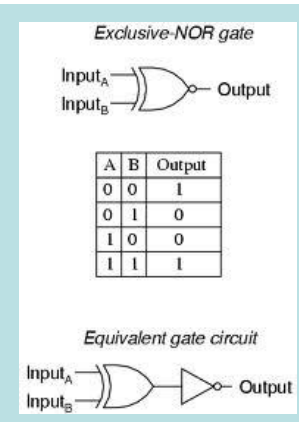
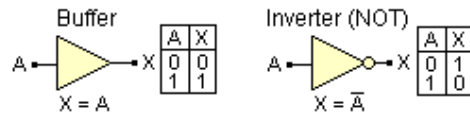
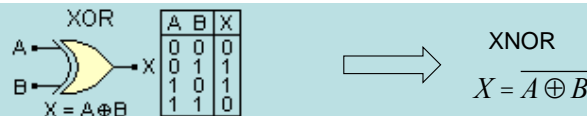
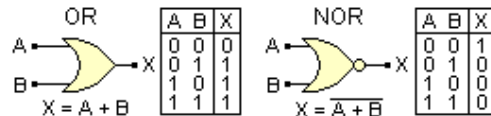
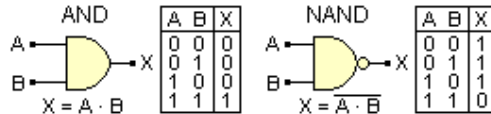
OR operation

Truth Table OR

X	Y	Z
0	0	0
0	1	1
1	0	1
1	1	1



7432 integrated circuit provides four (Quad) two-inputs OR gates



Resource: <http://www.chem.uoa.gr/applets/appletgates/Images/Image1.gif>

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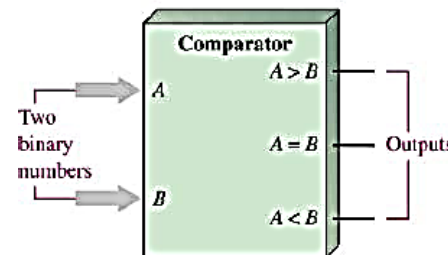
Overview of Logic Functions

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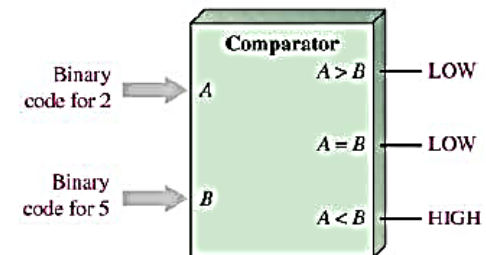
Basic Logic Functions

- ❑ Any digital systems has one or more of the following function.
- ❑ This functions are built from the basic gates.
 - Comparison Function
 - Arithmetic Functions
 - Code conversion function
 - Encoding function
 - Decoding function
 - Data selection function
 - Data storage function
 - Counting function

Comparison Function



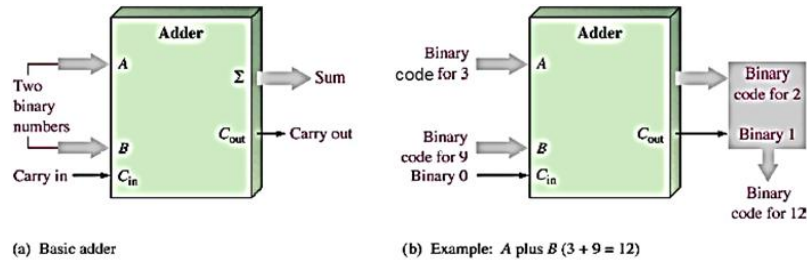
(a) Basic magnitude comparator



(b) Example: A is less than B (2 < 5) as indicated by the HIGH output (A < B)

Arithmetic Functions

• Adder



- Subtractor
- Multiplier
- Division

All the other arithmetic operations can be derived from adder:

- ❑ Subtraction is and addition of negative number such as $A - B = A + (-B)$
- ❑ Multiplication is a repeated addition such as $A * 3 = A + A + A$
- ❑ Division is a repeated subtraction which is a repeated addition such as $6/3 = 6 - 3 - 3 = 6 + (-3) + (-3)$
 - subtract until the remainder = 0
 - total number of subtraction = 2 which is the answer

Resource: Floyd, Digital Fundamentals, 10th Edition

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Code Conversion Function

- A code is a set of bits arranged in a unique pattern and used to represent specified information.
 - Examples : BCD, ASCII
- The usage of codes allow a faster and more efficient data processing.



http://www.ehow.com/how_7162480

只要去探
之所不在

symbols.com



<http://facebooksmileysinfo.com/wp-content/uploads/2012/04/Smiley-Facebook-emoicons.jpg>

و ذ خ ه ت
ج ص م ظ
ث ح و ك
ي ع ل ا ئ
ا س ل ب ش

<http://depositphotos.com/2746252/stock-illustration-Arabic-alphabet.html>



<http://allenmathblog.files.wordpress.com/2012/01/integers.jpg>

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To send this:



Type this:

:-) or :)
:-O or :o
;-) or ;) :S or :s
:-(
(H) or (h)
(A) or (a)
:-#
8-|
8-|
:-*
:^)
<:o)

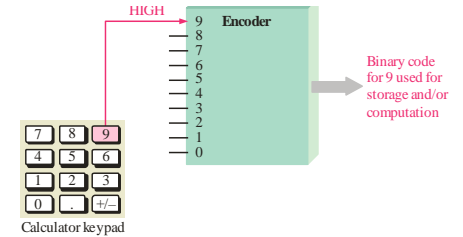
Ctrl	Dec	Hex	Char	Code	Dec	Hex	Char	Dec	Hex	Char	Dec	Hex	Char
^@	0	00	NUL	32	20	!	64	40	@	101	65	f	
^A	1	01	SOH	33	21	!"	65	41	A	102	66	g	
^B	2	02	STX	34	22	."	66	42	B	103	67	h	
^C	3	03	ETX	35	23	#"	67	43	C	104	68	i	
^D	4	04	END	36	24	\$"	68	44	D	105	69	j	
									E	106	6A	k	
									F	107	6B	l	
									G	108	6C	m	
									H	109	6D	n	
									I	110	6E	o	
									J	111	6F	p	
									K	112	70	q	
									L	113	71	r	
									M	114	72	s	
									N	115	73	t	
									O	116	74	u	
									P	117	75	v	
									Q	118	76	w	
									R	119	77	x	
									S	120	78	y	
									T	121	79	z	
									U	122	7A	{	
									V	123	7B	}	
									W	124	7C	~	
									X	125	7D		
									Y	126	7E		
									Z	127	7F		
									[
									\				
]				
									^				
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Extra

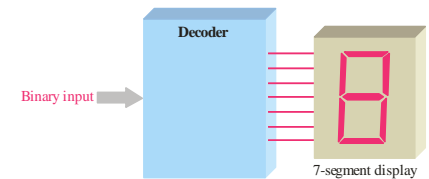
* ASCII code 127 has the code DEL. Under MS-DOS, this code has the same effect as ASCII 8 (BS).
The DEL code can be generated by the CTRL + BKSP key.

Encoding & Decoding Function

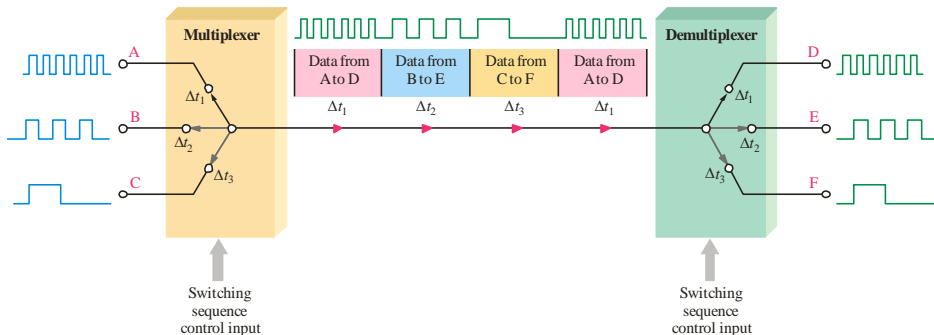
The encoding function



The decoding function



Data Selection Function: MUX & DeMUX



Problem:

Many inputs (e.g. A, B and C) wanted to use a single transmission line for their data transmission. How to make sure the data is transferred in a proper manner (issue of cost, synchronization, conflict, crash, loss?)

Source (A, B, C) and Destination (D, E, F)

A → D, B → E, C → F

Solution:

MUX: select and permit only one device can use the line and transfer its data at one time.

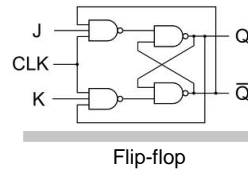
Data in the transmission line would be arranged as A, B, C

DEMUX: select and route the data to their originate destination

A → D, B → E, C → F

Data Storage Function

- Flip-flop stores a 1 or 0 only
- Registers
 - Formed by combining several flip-flops
 - 8-bit register → from 8 flip-flops
- Semiconductor Memories
 - e.g. RAM, ROM, Flash
- Magnetic/Optical Memories
 - For mass storage → e.g. hard disk, tape, DVD, Blu-Ray

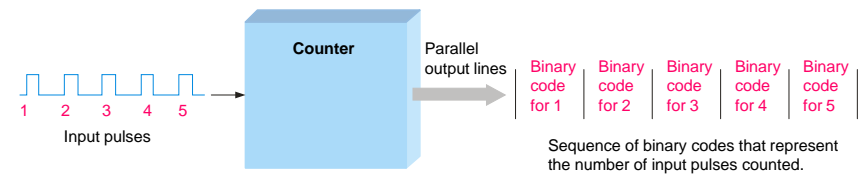


Counting Function

Examples:

- Traffic light
- Washing machine
- Vending machine
- Xerox machine
- ATM machine
- etc.

- Counter
 - To count the occurrence at the input.
 - to initiate a controller after a certain count (period).



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Resource: Floyd, Digital Fundamentals, 10th Edition

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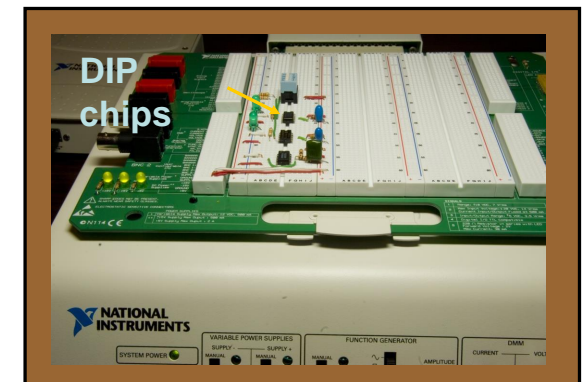


www.utm.my

Fixed-Function Integrated Circuit (IC)

An example of laboratory prototyping is shown. The circuit is wired using DIP chips and tested.

In this case, testing can be done by a computer connected to the system.



(Dual In-line Package)

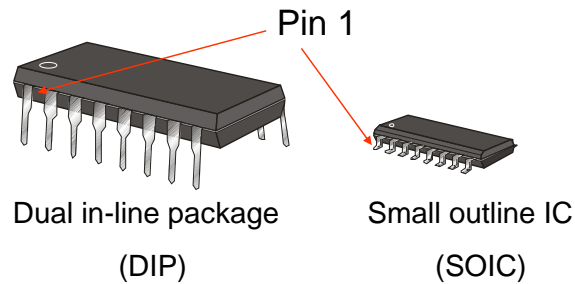
63

Resource: Floyd, Digital Fundamentals, 10th Edition

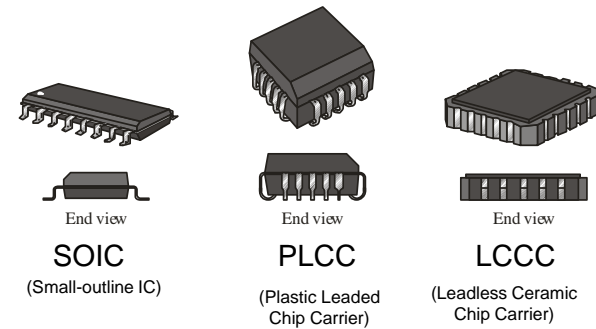
64

IC Packages

DIP chips and surface mount chips



Other surface mount technology (SMT) packages:



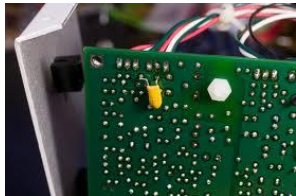
Resource: Floyd, Digital Fundamentals, 10th Edition

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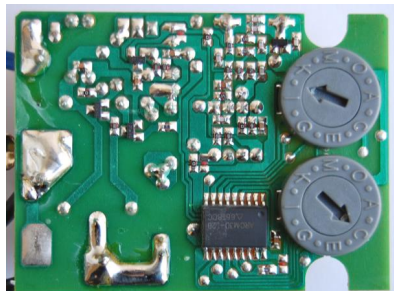
Resource: Floyd, Digital Fundamentals, 10th Edition

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IC and conventional through-hole technology



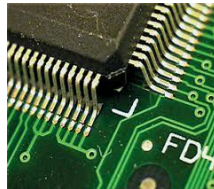
<http://aa7ee.wordpress.com/page/4/>



<http://jeelabs.org/tag/teardown/>

Printed Circuit Board (PCB)

Surface Mount PCB



<https://neuromorphs.net/ws2007/wiki/smd>

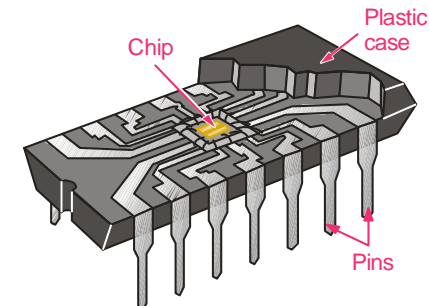


<http://www.pcb-manufacturers.co.uk/pcb-production-examples-c.html>

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Integrated circuit

Cutaway view of DIP (Dual-In-line Pins) chip:



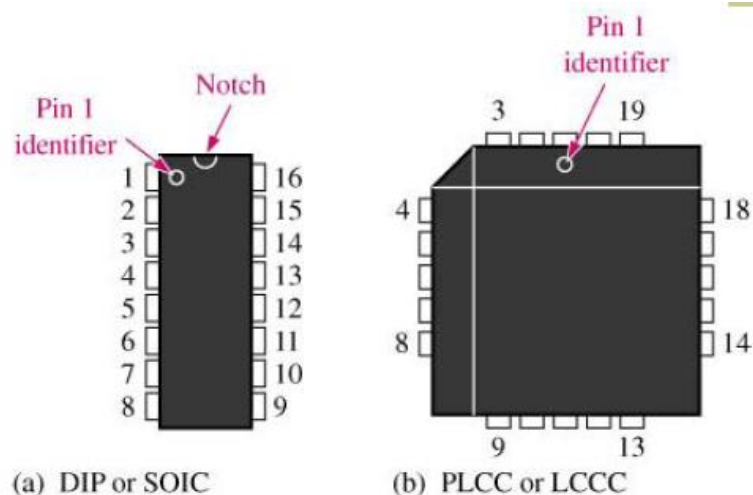
IC Packaging: Why we need packaging?

- To protect the IC (circuit)
- Have a pin system so that can connect to other circuit

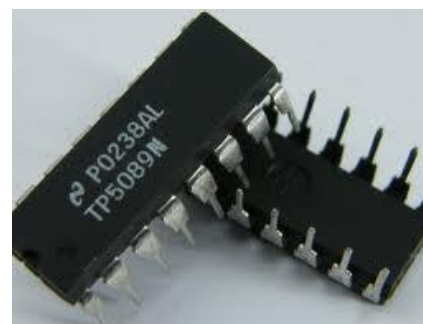
Resource: Floyd, Digital Fundamentals, 10th Edition

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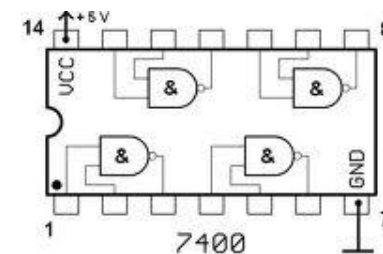
Pin Numbering



<http://www.rkonlinestore.co.uk/555-dual-timer-ic-16-pin-dip-pack-of-4-391-p.asp>



<http://www.ebay.com/itm/10pcs-IC-TP5089N-DIP-16-PIN-TP5089-310306081949>



<http://electroschematics.com/6529/7400-datasheet/>

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Complexity Classifications for Fixed-Function ICs

- Small-scale integration (SSI) have up to 12 gates on a single chip
- Medium-scale integration (MSI) have from 12-99 gates on a single chip
- Large-scale integration (LSI) have from 100-9999 gates on a single chip
- Very large-scale integration (VLSI) have from 10,000-99,999 gates on a single chip
- Ultra large-scale integration (ULSI) have from 100,000 and greater equivalent gates on a single chip

Module 1



http://www.visual6502.org/images/263P/SSI_263P_8404_chip1_package_top.jpg



<http://www.nysemagazine.com/lisicorp>

Integrated Circuit Technologies

Some examples of IC technologies:

- TTL (Transistor-transistor Logic)
- ECL (Emitter-Coupled Logic)
- CMOS (Complementary Metal-Oxide-Semiconductor)
- NMOS (N-Type Metal-Oxide-Semiconductor)
- BiCMOS (Bipolar and Metal-Oxide-Semiconductor)



CMOS –

<http://www.creativecomputingnetwork.com/dcp/news/cmos-technology-primer/>

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Programmable Logic Devices (PLD)

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Overview of PLD

□ Fixed function

- A specific logic function is contained in the IC (hardwired) and can never be changed.

□ PLD

- Logic function programmed by the user.
 - Some, can be reprogrammed many times.
- Advantage
 - More logic circuit can be 'stuffed' into much smaller area.
 - Certain PLD, design can be changed without rewiring or replacing components.
 - Can be implemented faster once the required programming language is mastered.

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Types of PLD

3 major types (SPLD, CPLD, FPGA)

1. Simple Programmable Logic Devices (SPLD)

- Can replace several fixed-function SSI or MSI
- First type available
- A few categories
 - PAL (programmable Array Logic)
 - GAL (Generic Array Logic)
 - PLA (Programmable Logic Array)
 - PROM (Programmable Read-Only memory)

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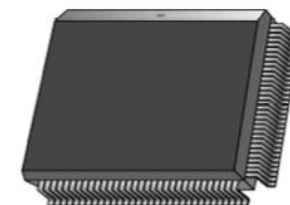
Types of PLD: CPLD

2. Complex Programmable Logic Devices (CPLD)

- Much higher capacity than SPLD (2-64 SPLD)
 - More complex logic circuits can be programmed
 - Typically in 44 – 160 pin package



(a) 84-pin PLCC package



(b) 128-pin PQFP package



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Types of PLD: FPGA

- 3. Field-Programmable Gate Arrays (FPGA)
 - Different internal organization than SPLD and CPLD
 - Greatest logic capacity
 - Consist of 64- thousands logic block (logic gate groups)
 - Classes
 - Fine grain (smaller logic block)
 - Coarse grain (large logic block)

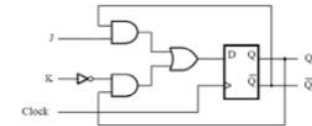


Resource: http://upload.wikimedia.org/wikipedia/commons/thumb/f/fa/Altera_StratixIVGX_FPGA.jpg/300px-Altera_StratixIVGX_FPGA.jpg

PLD Programming

- Logic circuit entered using 2 basic method

- Graphical entry
 - schematic diagram



- Text-based entry (language based entry)

- Using Hardware Description Language (HDL)

- Eg . ABEL, CUPL, WinCUPL
- Becoming widely used especially for CPLD and FPGA
 - VHDL
 - Verilog

```
MODULE decoder
TITLE 'decoder'
A,B,C,D      pin      1,2,3,4;
W,X,Y,Z      pin      14,15,16,17;

equations
W=!B & C # !B & D # C & D # A;
X=!A & D # B # C;
Y=!A & !B & D # C;
Z=!B & C # D;
```

Resource: Floyd, Digital Fundamentals, 10th Edition