

Assignment 4
ERROR AND NONLINEAR SOLUTIONS

Question 1

- a) If a speedometer's absolute error is 2 mph and it measures a speed of 60 mph, what is the relative error of this measurement expressed as a percentage?
- b) Find the absolute error for $f'(2)$ for $f(x) = x$, given that

$$f'(x) \approx \frac{f(x+h) - f(x)}{h} \text{ and } h = 0.1.$$

- c) Find the most accurate value for the following operation where each number has been rounded to a certain decimal point:

$$6.232 + 7.0321 + 5.43 - 3.385$$

Question 2

Find a root of the equation

$$x^6 - x - 1 = 0 \quad \text{accurate to within } \varepsilon = 0.001.$$

In $[1, 2]$ using bisection method.

Question 3

For a non-linear function, $f(x) = \cos(x) + 2 \sin(x) + x^2$, find the root using the following method:

- a. Secant method, $x_0 = 0$; $x_1 = -0.1$
- b. Newton method, $x_0 = -0.1$

Then, give some comments by comparing your results between these two methods. Do calculation in 4 decimal points and approximate the root in 2 decimal points.

Question 4

In his final maths exam, Ahmad needs to solve the equation

$$1/x = 1.37$$

However, his calculator has a problem where it only can add, subtract and multiply. Help Ahmad to solve this equation using the Newton method and the defective calculator.

- i) Prove that Newton formula can be written as

$$X_{n+1} = x_n(2 - \alpha x_n), \quad \text{if } \alpha = 1.37$$

- ii) Then used formula in (i) to find x correct to 8 decimal places if $x_0 = 0.75$

Question 5

Use characteristic polynomial to find the eigen value and eigen vector for A

$$S = \begin{bmatrix} 1 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 1 \end{bmatrix}$$

Question 6

1. Matrix B is given as follows,

$$B = \begin{bmatrix} -18 & 20 & -6 \\ -12 & 14 & -3 \\ 30 & -30 & 13 \end{bmatrix}$$

- Use the Gerschgorin's Circle Theorem to determine a region containing all the eigenvalues of B .
- Find the dominant eigenvalue (λ_1) and the corresponding eigenvector of matrix B using Power method. Use $\mathbf{v}^{(0)} = [0, 0, 1]^T$.
- Find the smallest eigenvalue (λ_3) and the corresponding eigenvector of matrix B using Shifted Power method. Use $\mathbf{v}^{(0)} = [0, 0, 1]^T$.
- Find the intermediate eigenvalue (λ_2) of matrix B .

Note: Do calculation in 4 decimal points with $\varepsilon = 0.05$. Round up the dominant eigenvalue (λ_1) in (b) and the smallest eigenvalue (λ_3) in (c) to the nearest integer.